



Magnetotelluric inversion with wavelet sparsity regularization

C. Nittinger¹, M. Becken¹

¹University of Münster, Institute of Geophysics, Correnstr. 24, 48149 Münster,

Contact: cnittinger@wwu.de

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Smoothing regularization in Magnetotellurics – an inevitable tool?

Occam's inversion: A practical algorithm for generating smooth models from electromagnetic sounding data

Steven C. Constable*, Robert L. Parker*, and Catherine G. Constable*

ABSTRACT

Investigate a new algorithm for computing regularized solution of the Occam approach. Computational costs associated with constructing a 3D matrix in the Occam approach to 3D MT inversion are impractical. These difficulties are overcome by using a sparse matrix approach. The algorithm employs a gradient (NLGG) scheme to minimize an objective function that includes first and second spatial derivatives of resistivity. We compare this algorithm with the Occam approach.

Occam's inversion to generate smooth, two-dimensional models from magnetotelluric data

C. deGroot-Hedlin* and S. Constable*

Abstract

Three-dimensional magnetotelluric (MT) minimum structure inversion algorithm of the Occam approach. Computational costs associated with constructing a 3D matrix in the Occam approach to 3D MT inversion are impractical. These difficulties are overcome by using a sparse matrix approach. The algorithm employs a gradient (NLGG) scheme to minimize an objective function that includes first and second spatial derivatives of resistivity. We compare this algorithm with the Occam approach. Computational time by more than 70%, without affecting the inversion results. Reasonable fits can be obtained within a small number of iterations, with necessary structure and find the model with minimum norm. © 1994 Elsevier B.V. All rights reserved.

Magnetotelluric inversion for minimum structure

J. Torquil Smith* and John R. Booker*

ABSTRACT

Structure can be measured in terms of a norm of the derivative of a model with respect to a function of depth $f(z)$, where the model $m(z)$ is either the conductivity σ or $\log \sigma$. An iterative linearized algorithm can find models

Others result in smooth fits. At low frequencies, a "red" fit is a robust statistic is used. A regularization is made acceptably

Regularization is needed for a stable solution

Regularization

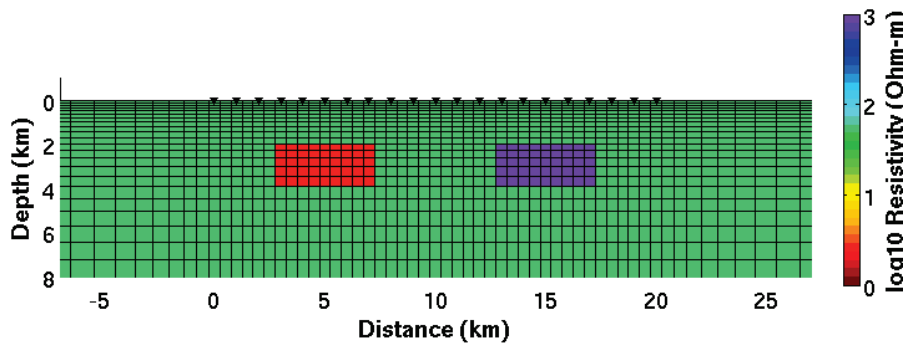
- Inverse problem:

$$\min \left\{ \underbrace{\| G(m) - d^{obs} \|_2^2}_{\text{data term}} + \underbrace{\lambda \Phi(m)}_{\text{regularization}} \right\}$$

- Objective: smoothest possible representation of the model that fits the data
- non-linear and ill-posed problem
→ infinite number of solutions

- L2-Norm: $\Phi(m) = \sqrt{\sum |m|^2}$
→ smoothness

How to describe a resistivity model?



Usual inversion grid:

- Piecewise constant functions
- **Many** Blocks

Compressed model described by wavelets: [Daubechies, 1992]

$$m(x) = \sum_j^M c_j \Phi_j(x) = \underbrace{\sum_j a_j \Phi_j(x)}_{\text{Approximation Coeffs.}} + \underbrace{\sum_j \sum_k d_k^j \Psi_{j,k}(x)}_{\text{Detail Coeffs.}}$$

j - translation
k - scale

- **few** coefficients
→ no loss of Information

Can we benefit from sparse inversion?

Sparse Inversion: Regularize for sparsity of wavelet coefficients

→ applications in various fields:
 medical imaging, image processing,
 signal analysis, seismic tomography

- No structural penalty
- Model structures dependent on chosen wavelet basis
 → can be sharp, smooth or both.

Regularization

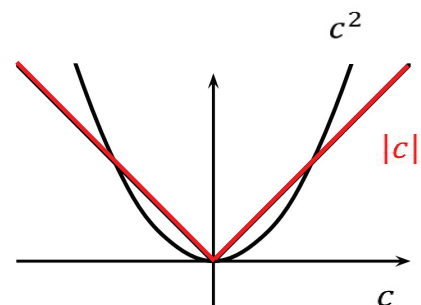
- Inverse problem:

$$\min \left\{ \underbrace{\| G(c) - d^{obs} \|_2^2}_{\text{data term}} + \underbrace{\lambda \Phi(c)}_{\text{regularization}} \right\}$$

- Objective: **sparsest** possible representation of the model that fits the data

- L2-Norm: ~~$\Phi(m) = \sqrt{\sum |m|^2}$~~
 → smoothness

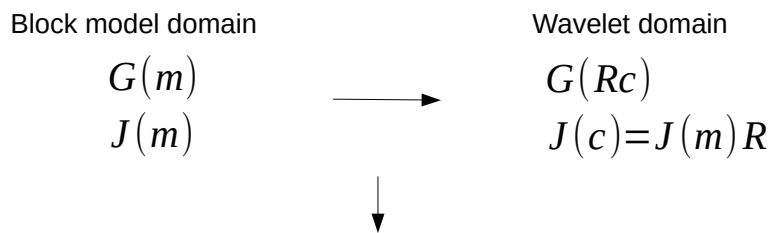
- L1-Norm: $\Phi(c) = \sum |c|$
 → sparsity



Objective function in Wavelet domain

$$\Phi(c, m) = \|G(m) - d^{obs}\|_2^2 + \lambda \|c\|_1$$

- Wavelet Transformation: $m = Rc$
- Finite element forward code by Lee et al. (2009)



$$\Phi(c) = \|W_e(G(c) - d^{obs})\|_2^2 + \lambda \|c\|_1$$

Gauss Newton approach to solve linearized objective

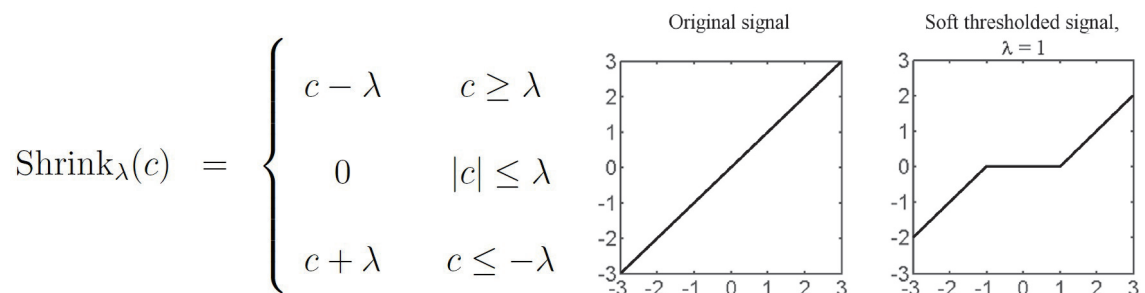
- Linearized Iteration step:

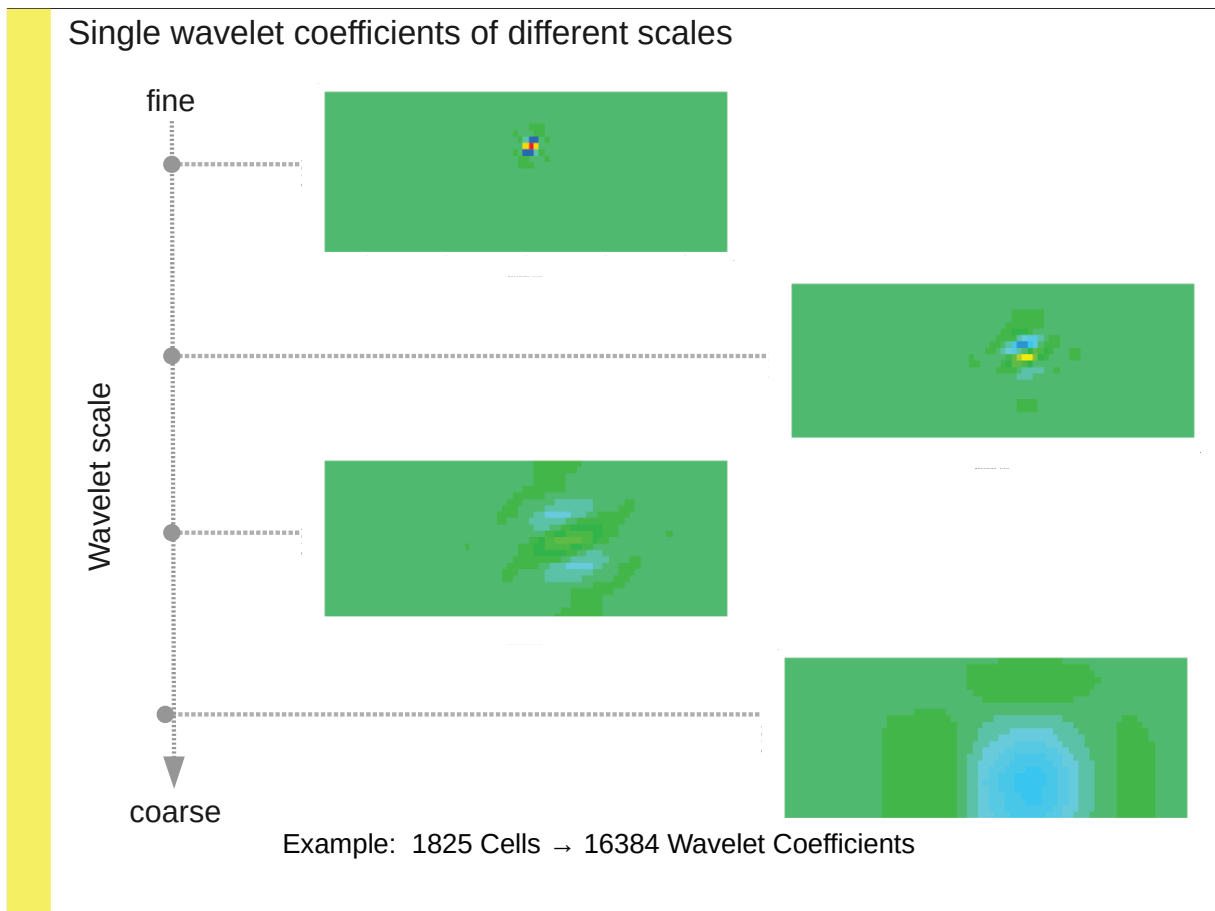
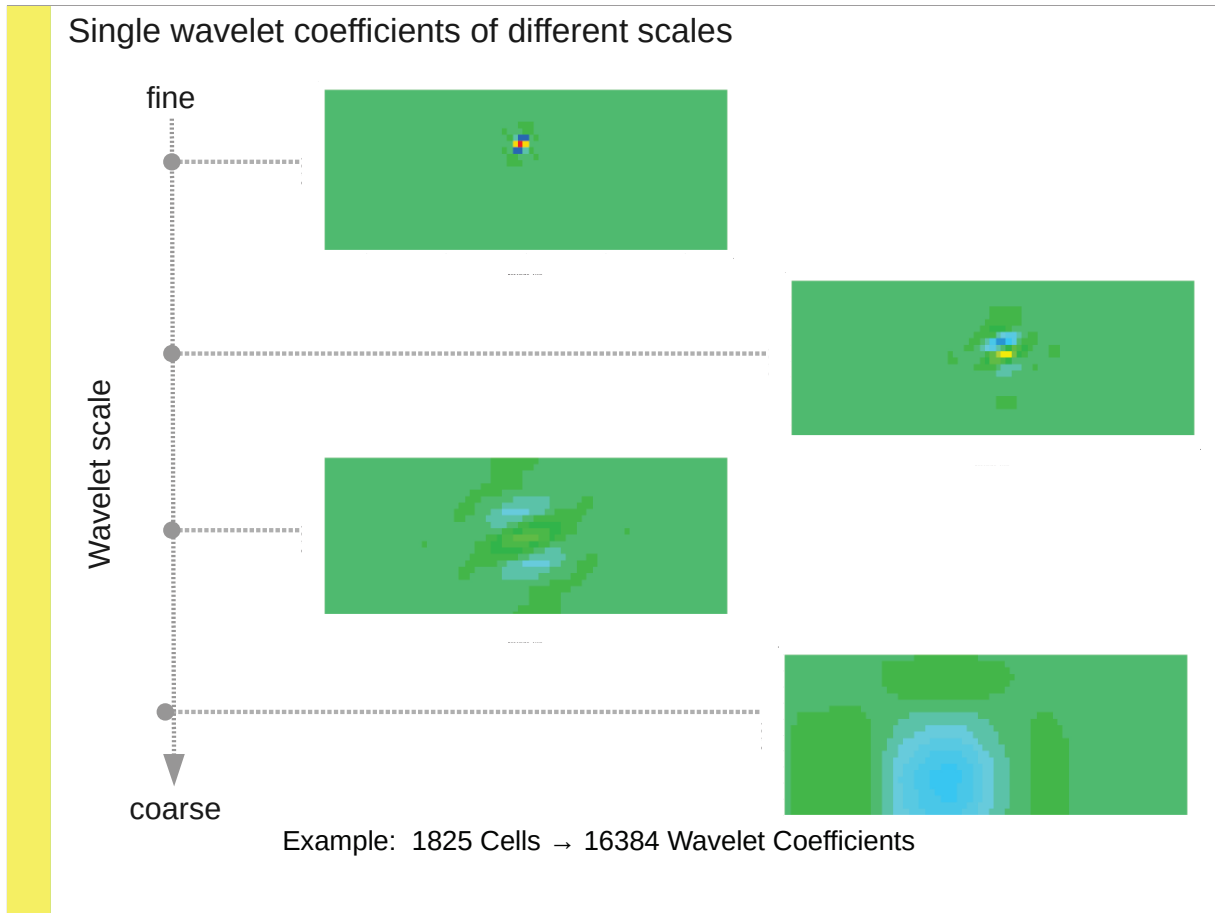
$$\|W_e(J(c^k)c^{k+1} - \hat{d}(c^k))\|_2^2 + \lambda \|c^{k+1}\|_1 \rightarrow \min.$$

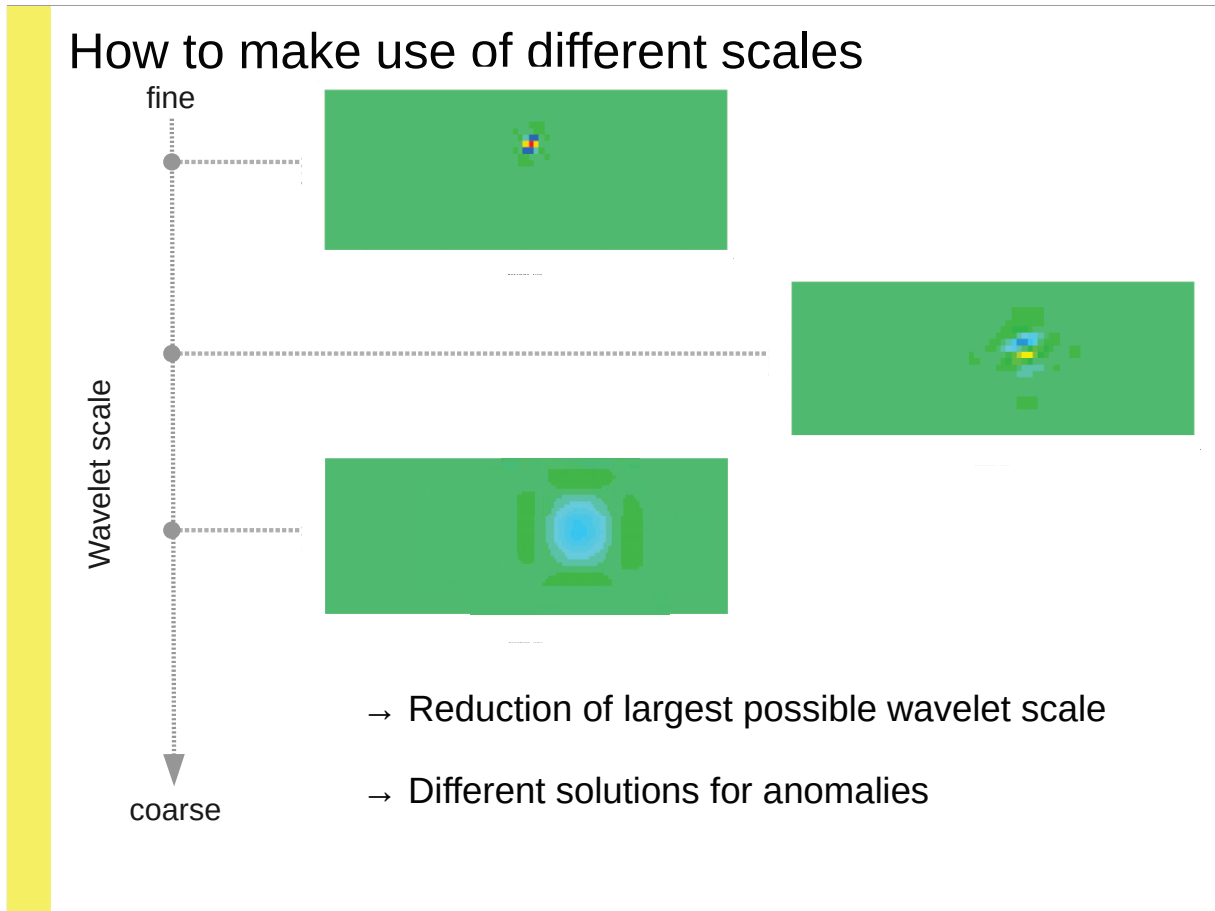
$$\hat{d}(c^k) = d^{obs} - G(c^k) + J(c^k)c^k$$

- Solve with iterative soft thresholding (IST) by Daubechies et al. (2004)




$$c_{n+1}^{k+1} = \text{Shrink}_\lambda \left(c_n^{k+1} + (W_e J(c^k))^T (W_e (\hat{d}(c^k) - J(c^k)c_n^{k+1})) \right)$$





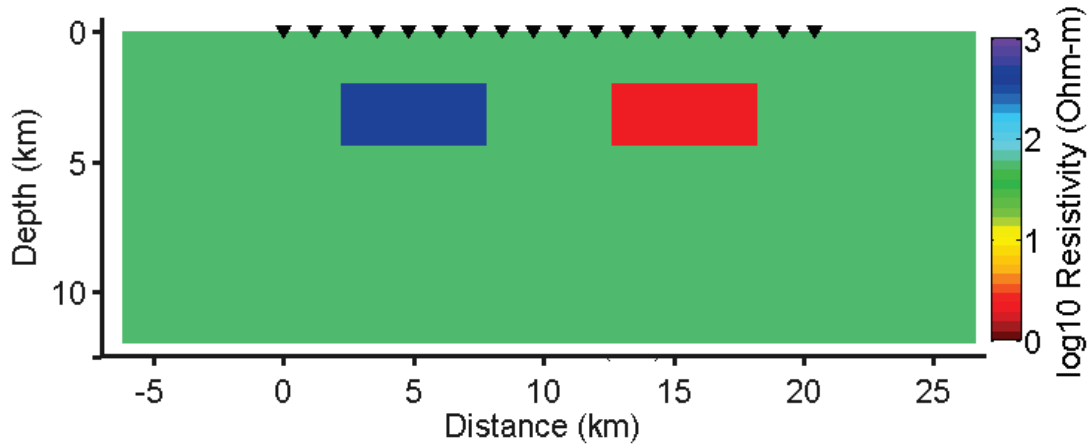


Inversion of magnetotelluric data in a sparse model domain

-  Sparsity regularization
-  Model Representation
-  Synthetic examples

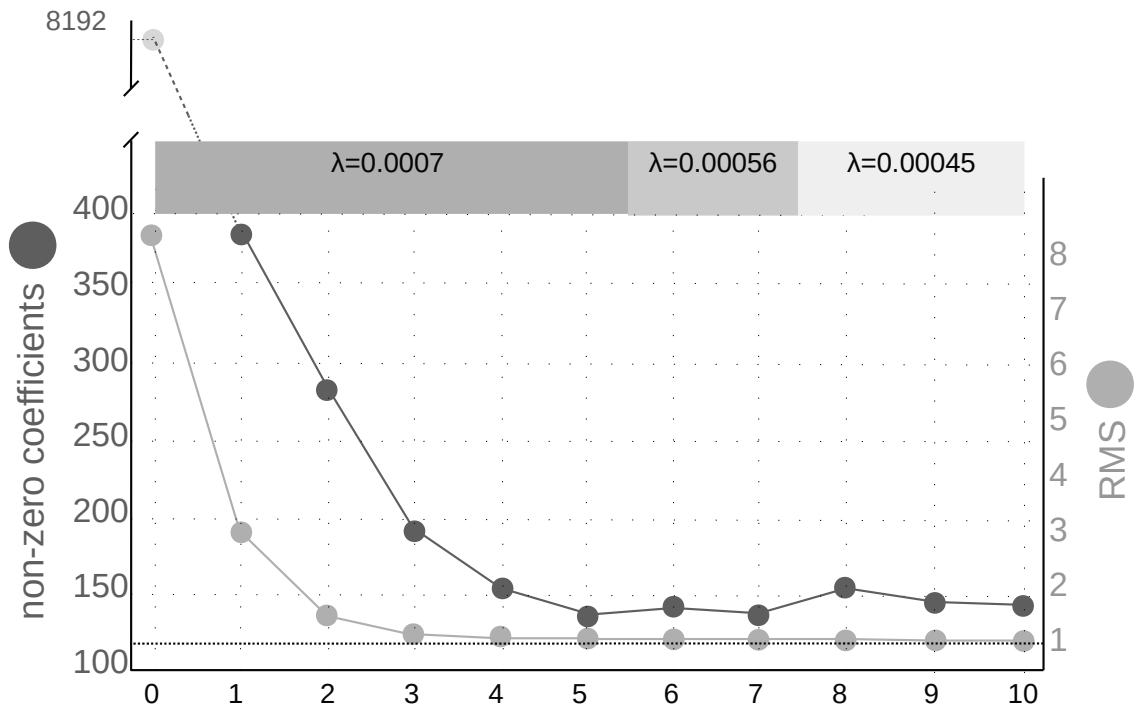
True model

Errors: App. Res. 5%
Phase 1°
Tipper 0.05



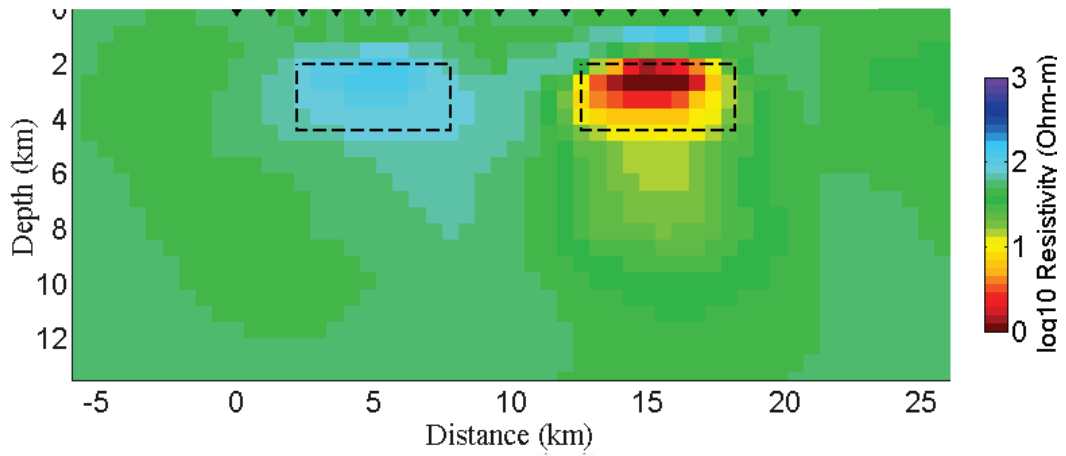
Grid: 55x20 uniform cell sizes of 600m
Freq.: 0.1s-100s

Sparsity of Iteration steps



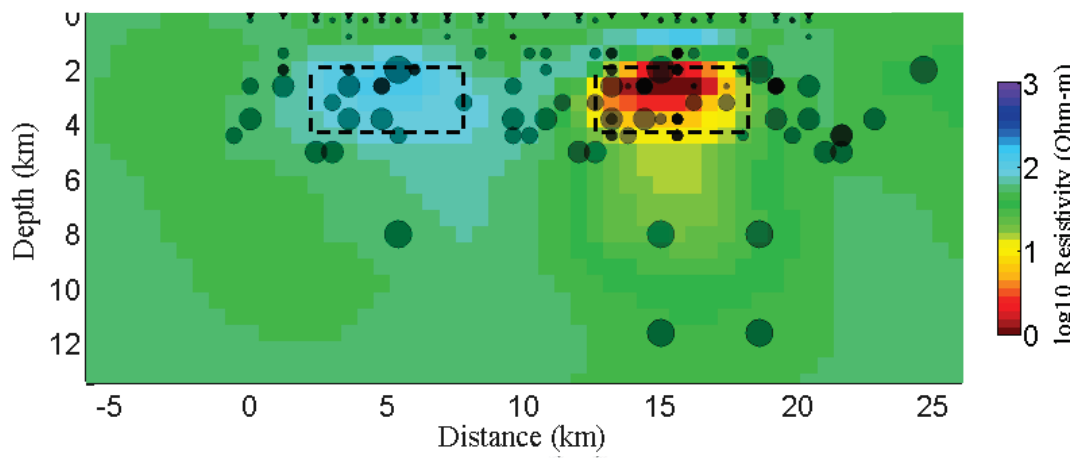
Inverse model

Coeffs: 143 RMS: 1.03



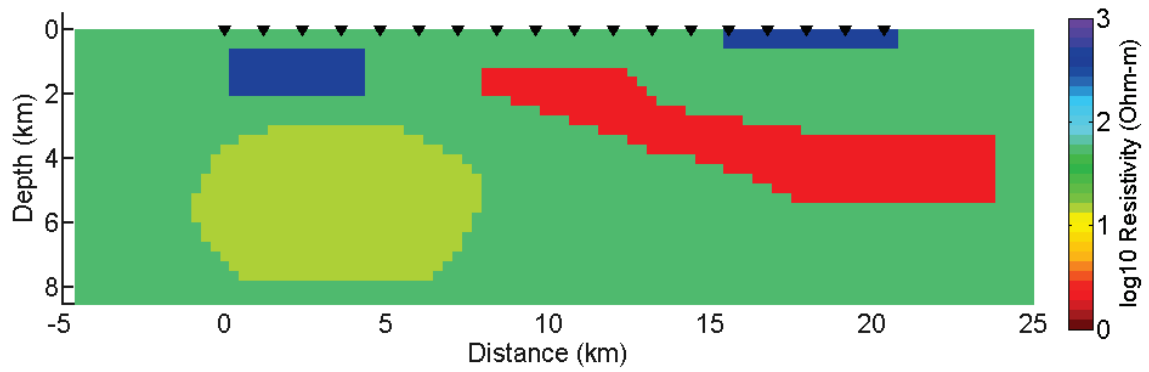
Inverse model

Coeffs: 143 RMS: 1.03



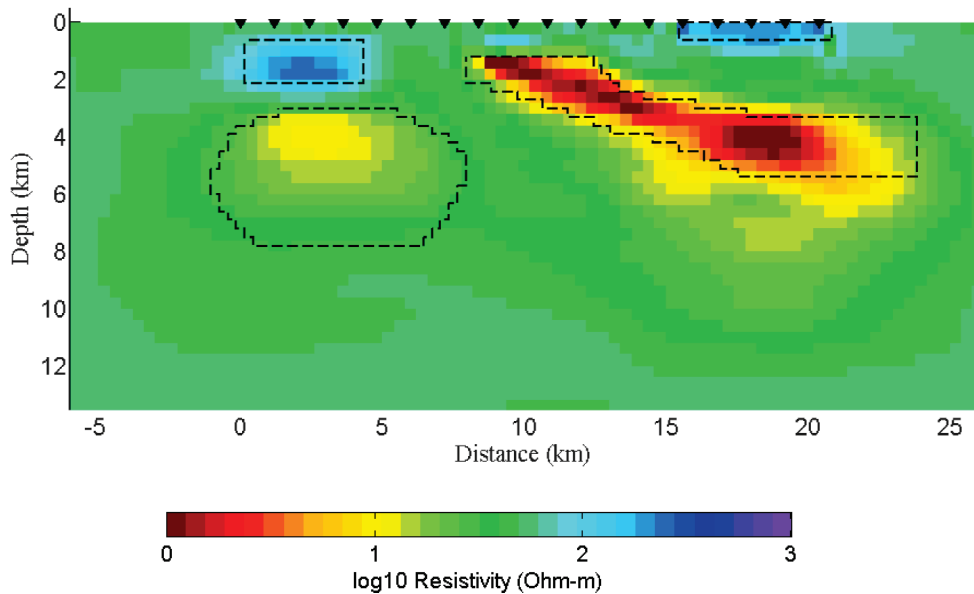
True model

Errors: App. Res. 5%
Phase 1°
Tipper 0.05



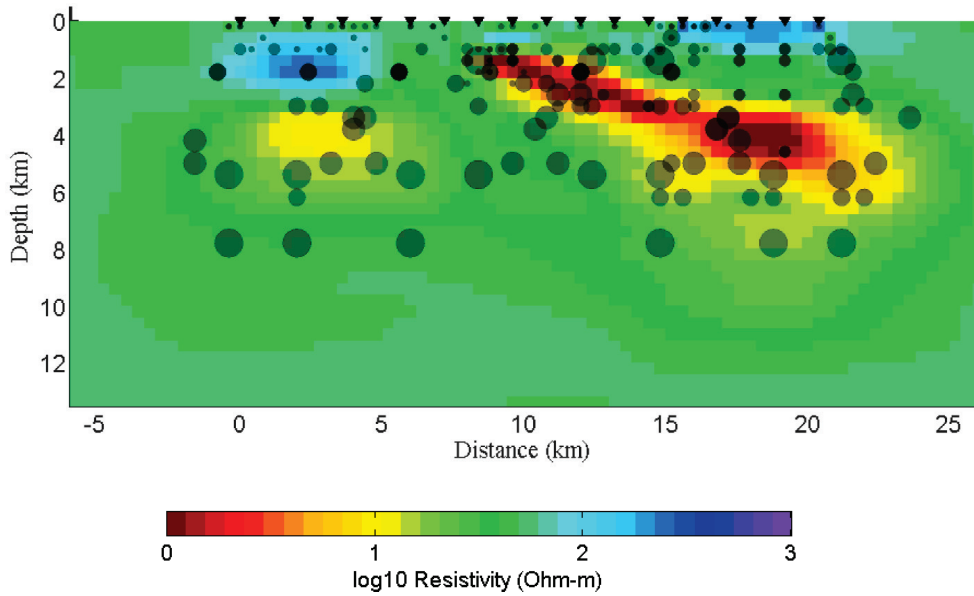
Inverse model

Coeffs: 199 RMS: 1.05 Max scale: 4

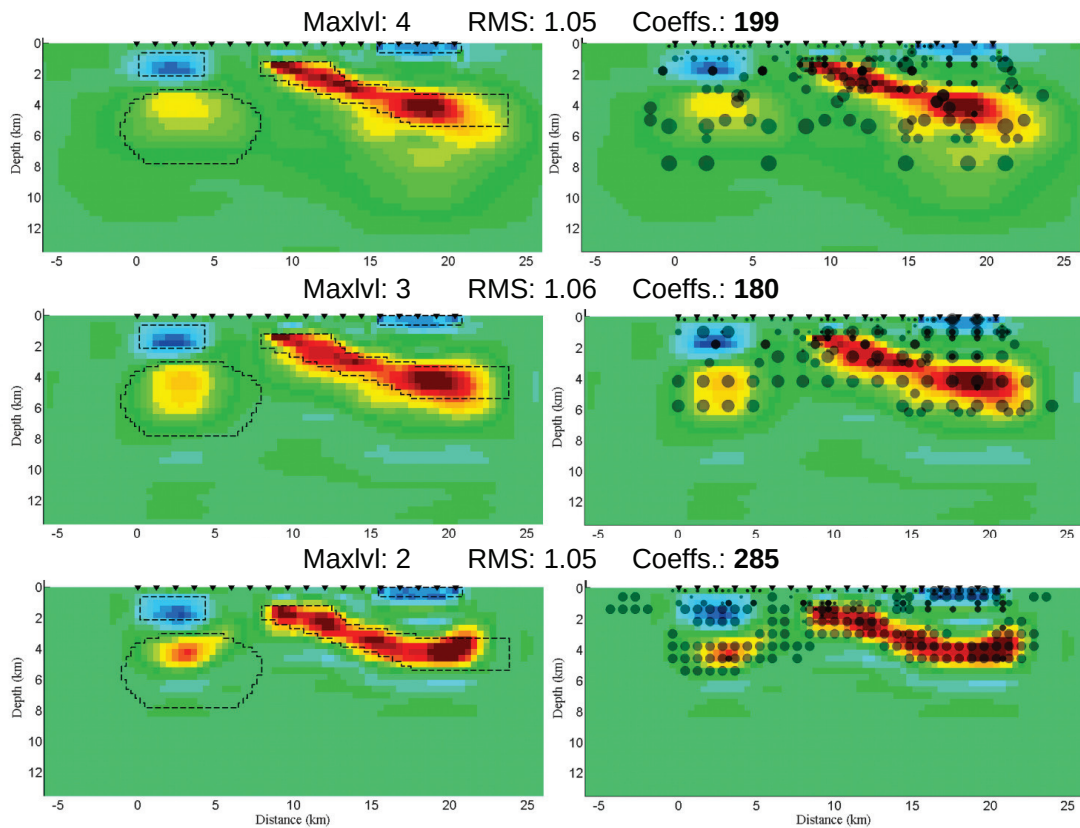


Inverse model

Coeffs: 199 RMS: 1.05 Max scale: 4

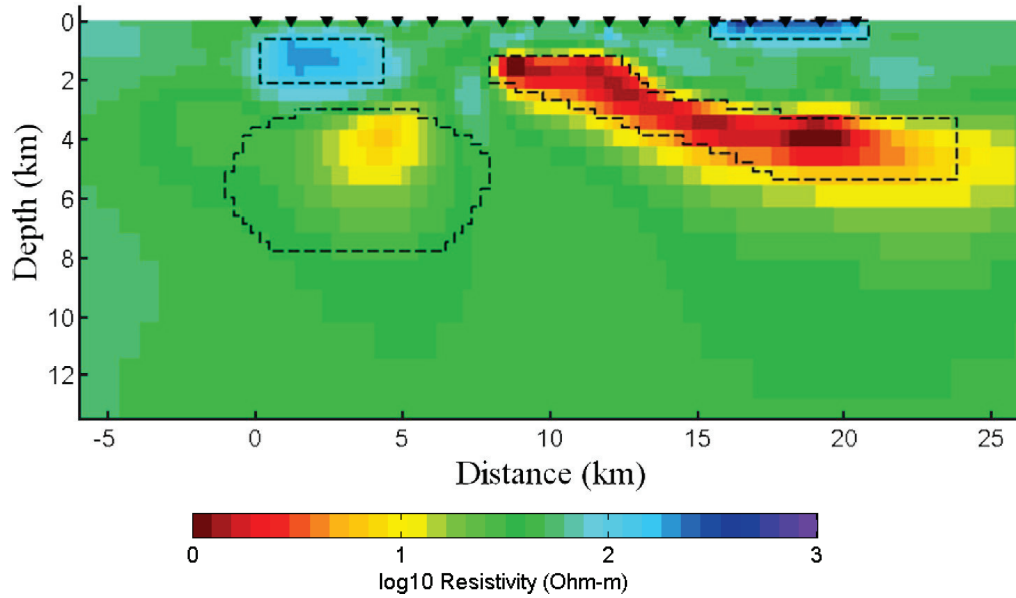


Reduction of maximal scale



Smooth Inversion model is very similar

RMS: 1.02

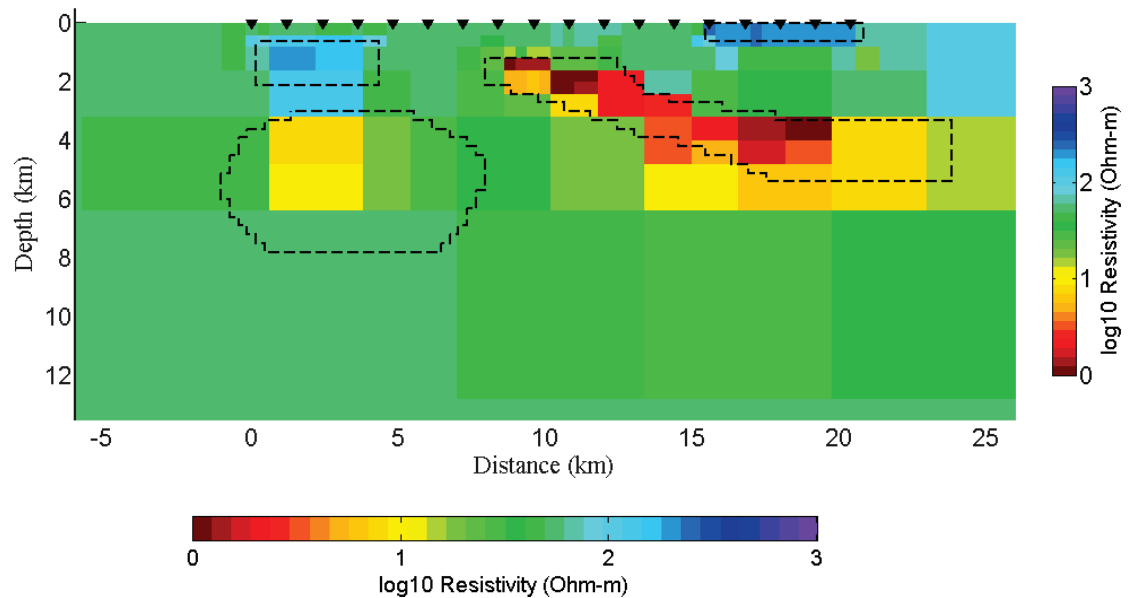


The Haar wavelet representation

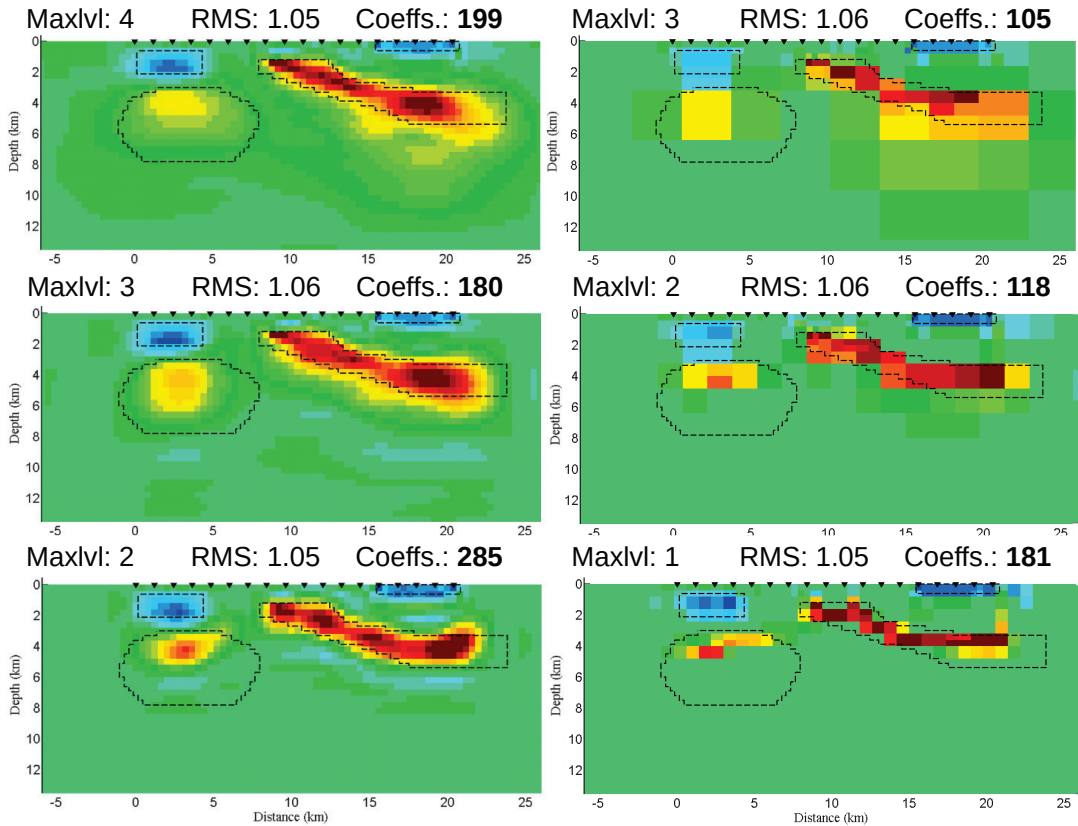
Coeffs: 96

RMS: 1.05

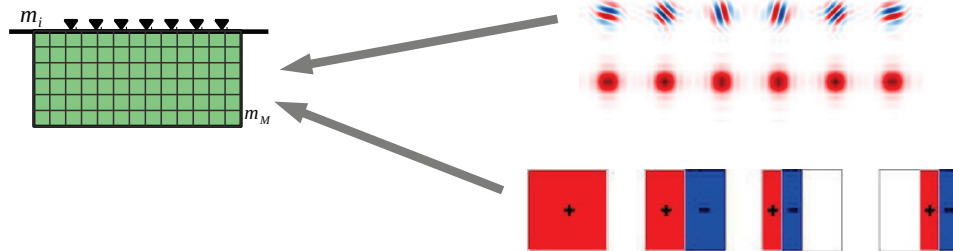
Max Scale: 4



Inverse model



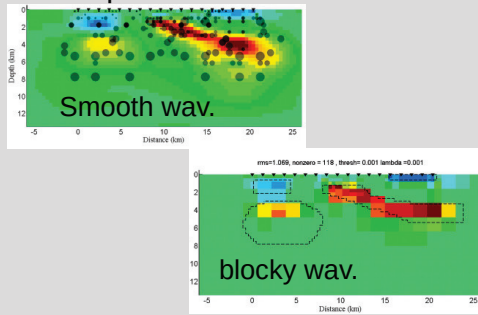
Summary



L1-Norm Regularization of c :

$$\Psi(c) = \lambda \|c\|_1$$

Sparse inversion model



Model Evaluation:

- Determine possible scales of anomalies
- Different representations allow comparison of different models
- Evaluation of non-unique model structures and artifacts



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