



Originally published as:

Akilan, A., Azeez, K. K. A., Balaji, S., Schuh, H., Srinivas, Y. (2015): GPS derived Zenith Total Delay (ZTD) observed at tropical locations in South India during atmospheric storms and depressions. - *Journal of Atmospheric and Solar-Terrestrial Physics*, 125-126, p. 1-7.

DOI: <http://doi.org/10.1016/j.jastp.2015.02.003>

1 **GPS derived Zenith Total Delay (ZTD) observed at tropical locations in South India**  
2 **during atmospheric storms and depressions**

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14

15 **Abstract**

16

17 Global Positioning System (GPS) monitoring of Zenith Total Delay (ZTD) of the  
18 troposphere which is related to water vapor is important as it may help us in weather  
19 forecasting. The atmospheric water vapor varies according to the season and it also varies  
20 quickly on short temporal and spatial scales during stormy periods. Thus it plays a crucial  
21 role in meteorology. GPS is one of the relatively inexpensive tools available to monitor the  
22 water vapor content in the atmosphere. In the present study, the efficacy of GPS data to  
23 monitor perturbations in tropospheric water content (GPS meteorology) associated with  
24 atmospheric storms and depressions is investigated utilizing the data from a tropical region of  
25 India, recorded between 15<sup>th</sup> October, 2010 and 27<sup>th</sup> December, 2010 during which Southern  
26 India was affected by a few significant atmospheric events. The ZTD was estimated for this  
27 period at the NGRI operated GPS stations at Hyderabad (HYDE) and MS University,  
28 Tirunelveli (MSUN). The accuracy of GPS derived ZTD was validated from the close match

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29 seen with ZTD values estimated from numerical weather modeling data. During the stormy  
30 periods there were strong variations of the ZTD. Corresponding changes in precipitable water  
31 vapor were estimated for the International GNSS Service station HYDE. The average ZTD  
32 was found to be higher near the coastal station at MSUN and less at the inland station HYDE.  
33 Most of the observed peaks in the ZTD time series were well correlated to the atmospheric  
34 events that influenced the region. The study extended to two more locations in the equatorial  
35 Indian Ocean region showed spatial variations in the ZTD values, which suggest the  
36 weakening of ZTD towards the coast. Our observations are yet another illustration for the  
37 application of GPS observations to monitor tropospheric water content variations associated  
38 with severe atmospheric events.

39 **Key Words:** GPS meteorology, Zenith Total Delay, precipitable water, atmospheric storms.

40

## 41 **1. Introduction**

42

43 The Global Positioning System (GPS) technology (Leick, 1990), which was originally  
44 designed as a system for navigational and time transfer, has revamped the field of geodesy  
45 and geodynamics by its ability to determine Earth rotation parameters and geodetic positions  
46 precisely with little costs. Later, e.g. Bevis et al. (1992) realized the relation between the  
47 Zenith Total Delay (ZTD) experienced by the GPS signal and the atmospheric water content,  
48 and GPS monitoring found another useful application in meteorological studies that opened  
49 the field of GPS meteorology (Businger et al., 1996). Today, remote sensing of the  
50 atmospheric parameters, i.e. ZTD obtained from GPS signal records, is useful in  
51 meteorological studies and successful in weather forecasting, thus making GPS meteorology  
52 a frontier area of research (e.g. Rocken et al., 1993; Bevis et al., 1994; Duan et al., 1996;  
53 Emardson et al., 1998; Foster et al., 2000; Baltink et al., 2002; Gradinarsky et al., 2002;  
54 Hagemann et al., 2003; Champollion et al., 2005; Jade et al., 2005; Jin et al., 2007; Nilsson  
55 and Elgered, 2008; Thomas et al., 2011; Joshi et al., 2013; Means and Cayan, 2013; Suparta  
56 et al., 2013; Wang et al., 2013; Singh et al., 2014a,b; Li et al., 2014). In this paper, we

57 demonstrate the correlation between the ZTD values estimated from continuous GPS  
58 monitoring, and atmospheric storm phenomena and rainfall associated with them to establish  
59 the utility of GPS monitoring for weather and rainfall forecasting.

60

61 The atmospheric water vapor causes a delay in the propagation of GPS radio signals, while  
62 passing through the atmosphere to the receivers on the Earth surface. This delay, known as  
63 ‘wet delay’, is approximately proportional to the quantity of water integrated along the ray  
64 path (Hogg et al., 1981; Askine and Nordius, 1987). Therefore, dynamic perturbations in the  
65 atmospheric water vapor content would get reflected in the ZTD values obtained from GPS  
66 studies, which correspond to the total GPS signal delay caused by the atmospheric column  
67 vertically above the GPS station. Knowledge of the spatial and temporal distribution of water  
68 vapor in the atmosphere is an important factor for a better understanding of atmospheric  
69 phenomena, climate and climate changes (Starr and Melfi, 1991). This atmospheric parameter  
70 commonly shows rapid changes with space and time, and hence becomes a crucial  
71 component of climate and weather modeling.

72

73 Storms on the Earth such as rainstorm, snowstorm, cyclonic storm, depression, etc. are severe  
74 weather conditions that are associated with notable transient changes in atmospheric water  
75 content. These sudden changes in precipitable water vapor (PWV) associated with the  
76 atmospheric events can be well picked up by the GPS data (e.g. Rocken et al., 1993). For the  
77 Indian sub-continent, weather forecasting is being successfully performed by the Indian  
78 Meteorological Department (<http://www.imd.gov.in>) using latest technologies. The present  
79 study utilizes GPS data to compute atmospheric parameters related to water content in the  
80 troposphere (ZTD and PWV), and evaluates the variations seen in these values to observe the  
81 signatures of storms and depressions. The GPS signals from two stations located in South  
82 India were analyzed to study the ZTD and also the PWV variations related to tropical  
83 cyclonic storms and deep depressions that were originated in the Indian Ocean and affected  
84 the Southern part of the East coast of the Indian Peninsula between 25<sup>th</sup> October, 2010, and  
85 11<sup>th</sup> December, 2010.

## 86 2. Basic concepts of GPS meteorology

87

88 The GPS radio waves travelling from satellites in space to the receiver on ground undergo  
 89 significant delay induced by the ionosphere and troposphere (the lower part of atmosphere,  
 90 Hogg et al., 1981). In geodetic studies, these ionospheric and tropospheric delays (together  
 91 known as the total delay) are removed by appropriate corrections applied to the GPS signals  
 92 (Davis et al., 1985). In the meteorological application of GPS we make use of the  
 93 tropospheric delay information as this is directly related to the constituent components of the  
 94 troposphere. This total tropospheric delay, called ZTD, is further divided into Zenith Wet  
 95 Delay [ZWD] and Zenith Hydrostatic Delay [ZHD], which are respectively due to the wet  
 96 water vapor and dry gaseous components in the troposphere (e.g. Nilsson and Elgered, 2008).  
 97 The ZTD can be determined after removing the ionospheric delay part from the total delay  
 98 computed from two-frequency GPS observations. The ZWD is proportional to the  
 99 tropospheric integrated water vapor content  
 100 ( $IWV = \int_0^{\infty} \rho_w dZ$ ;  $\rho_w$  – density of water vapor,  $dZ$  – vertical coordinate) and is the minor  
 101 component (~10 %) of the ZTD. The water vapor content of the atmosphere in zenith  
 102 direction is also defined as the height of an equivalent liquid water column and referred to  
 103 Precipitable Water ( $P_w$ ), which can be computed from ZWD using the relation (Nilsson et al.,  
 104 2013):

$$105 \quad P_w = k \Delta L_w^z \quad (1)$$

106 where,  $\Delta L_w^z$  is the ZWD and  $k = \frac{10^6 M_w}{\left[ k'_2 + \frac{k_3}{T_m} \right] R \rho_{wl}}$ , for which  $k'_2 = 16.52$  K/mbar, and  $k_3 =$   
 107  $(3.776 \pm 0.004) \times 10^5$  K<sup>2</sup>/mbar are constants (Askne and Nordius, 1987).

108  $M_w$  is the molar mass of water (18.0152 g/mol).

109  $T_m$  is the mean temperature  $\approx 70.2 + 0.72T_0$ , where  $T_0$  is Earth surface temperature

110  $R$  is the universal gas constant,  $R = 8.314$  J/mol, and

111  $\rho_{wl}$  is the density of liquid water in kg/m<sup>3</sup>

### 112 3. Data and analysis

113

114 As a part of its GPS-Geodesy program, the National Geophysical Research Institute  
115 (NGRI), Hyderabad, India initiated GPS monitoring at Hyderabad (HYDE) in the year 1995  
116 by establishing an IGS (International GNSS [Global Navigational Satellite Systems] Service  
117 – <http://www.igs.org>) tracking station. In September 2010, we started recording GPS signals  
118 at another GPS permanent station positioned at MS University campus, Tirunelveli, South  
119 India (hereafter called MSUN; Figure 1). Both these stations are within the Southern part of  
120 Indian Peninsula surrounded by the Indian Ocean. The geographic position and other details  
121 of these GPS stations are given in Table 1. The stations were equipped with multichannel  
122 dual frequency GPS receivers. A Leica System 1200 GRX GPS receiver was operative at  
123 HYDE and a Topcon GB 1000 GPS receiver was functioning at MSUN station. At both sites,  
124 the data were recorded with a uniform sampling rate of 30 seconds. The elevation cutoff  
125 angle of the GPS antenna was set to 5° to avoid the tracking of satellites at too low elevation.  
126 Multipath signals were mainly eliminated using choke ring antennas. The data in binary  
127 format were converted into Receiver Independent Exchange Format (RINEX) (Galas and  
128 Kohler, 2001).

129

130 The equatorial Indian Ocean region frequently is the origin zone of several severe  
131 weather conditions that affect the Indian subcontinent. The year 2010 has seen a few of such  
132 weather events and most of them were concentrated in the Bay of Bengal  
133 (<http://www.imd.gov.in/section/nhac/dynamic/RSMC-2010.pdf>). Among these, the very  
134 severe cyclonic storm ‘GIRI’ and the severe cyclonic storm ‘JAL’ were experienced during  
135 20-23 October and 4-8 November, 2010, respectively, and influenced the Indian weather  
136 conditions considerably. The cyclonic storm ‘JAL’ crossed the coasts of North Tamilnadu  
137 and South Andhra Pradesh on 7<sup>th</sup> November, 2010, while ‘GIRI’ did not hit the Indian coast  
138 and moved to the Myanmar coast. During 7-8 December, 2010, another depression was  
139 formed over the Bay of Bengal, which crossed the Southern Andhra Pradesh coast on 7<sup>th</sup>  
140 December, 2010. These events produced stormy weather and torrential rains in South India,

141 particularly on the East coast. We used about two and half months (15<sup>th</sup> October till 27<sup>th</sup>  
142 December, 2010, a period equivalent to the GPS day period 288-358) of GPS data recorded at  
143 the Hyderabad (HYDE) and Tirunelveli (MSUN) stations to estimate the ZTD perturbations  
144 over these locations. The ZTD data were further analysed to study their correlation with the  
145 atmospheric events and to identify typical signals corresponding to these meteorological  
146 events.

147

148 The raw GPS data in RINEX format were processed using the Bernese 5.0 software  
149 (Dach et al., 2007, 2009). Station MSUN was used as the fixed station for data processing. In  
150 the processing, the station position was fixed to the result of a preceding Precise Point  
151 Positioning (Melbourne, 1985). The Bernese software (Dach et al., 2007) was used for  
152 analyzing the GPS data. It assumes an azimuthally homogeneous atmosphere. Receiver clock  
153 errors, satellite clock errors and cycle slips were eliminated during processing and the  
154 ambiguities in the carrier phase were estimated and corrected. We applied the Niell mapping  
155 function (Niell, 1996), included in Bernese 5.0, to compute the ZTD values over Hyderabad  
156 and Tirunelveli stations. The temporal resolution was set to two hours; however, hourly  
157 estimations were made for the GPS period from day 326 to 329, which has seen heavy  
158 rainfall in and around Tirunelveli station.

159

#### 160 **4. Results and discussions**

161

162 The ZTD values computed for the period from 15<sup>th</sup> October to 27<sup>th</sup> December, 2010 at  
163 Hyderabad and Tirunelveli stations are presented in Figures 2 and 3. The variation in the  
164 hydrostatic delay that contributes 90% to the total ZTD value is a slow process and hence is  
165 negligible (e.g. Luo et al., 2013). Thus the observed variations in ZTD that contribute about  
166 10% to the absolute ZTD value mainly represent the changes in water vapor content in the  
167 troposphere. Our GPS derived ZTD time series show peaks and lows corresponding to the  
168 atmospheric water vapor changes associated with the severe weather periods experienced in

169 the region. To verify the reliability of GPS derived ZTD in establishing its relation with  
170 atmospheric weather changes, we compared our results with numerical weather model  
171 (NWM) data (e.g. Böhm et al., 2006; Bock et al., 2013). Numerical weather models are  
172 prepared continuously e.g. by the European Centre for Medium Weather Forecasting  
173 (ECMWF) [<http://www.ecmwf.int/>]. We used the ZTD data generated by numerical weather  
174 modeling studies from <http://ggosatm.hg.tuwien.ac.at/>, and compared them with our GPS  
175 derived observations. The comparison carried out for Hyderabad station data showed a  
176 remarkably good agreement of ZTD between the GPS derived and the numerical prediction  
177 values (Figure 2). In this case, the standard deviation between GPS and NWM estimations is  
178 0.004 m. Similar observation were also reported previously by Teke et al. (2013). The good  
179 match between GPS and NWM derived ZTD estimates was also confirmed from a t-test that  
180 showed more than 95% confidence level. We could not extend this to the MSUN site as this  
181 is not an IGS station and NWM data are not available for this location. As can be noticed  
182 from Figures 2 and 3, our GPS data suffer from a major data gap (~9 days between GPS days  
183 308 and 316) due to power failures at the MSUN site and hence the correlation was not  
184 possible for those few days without data recording. In addition to this, occasional data losses  
185 (GPS days 294-299, 332-336, and 341-343) were also evident in the time series. However,  
186 significant weather changes or rainfalls were not reported during those periods. The NWM  
187 data complement the GPS data and exhibit the ZTD behavior whenever GPS data are not  
188 available. We tested the good consensus shown between the GPS and NWM data using two  
189 other IGS GPS stations located in the equatorial Indian Ocean region. The GPS data from  
190 Cocos Island (COCO) and Diego Garcia (DGAR) were processed and the ZTD values were  
191 compared with the NWM ZTD values (Figure 4). The standard deviations obtained are 0.028  
192 m and 0.017 m at sites COCO and DGAR, respectively. Figure 4 again illustrates the good  
193 agreement between GPS derived and NWM calculated ZTD values, and thus allows us to use  
194 the information from numerical weather data whenever GPS could not record.

195

196 The rainfall data for the Hyderabad and Tirunelveli stations were also compared with the  
197 respective ZTD estimates to understand the correlation between the two (i.e. rainfall and ZTD



198 changes). The quantity of water in the atmosphere, i.e. precipitable water ( $P_w$ ), can be  
199 determined from ZTD using equation (1). The ZWD values (i.e.  $\Delta L_w^z$  term) needed in the  
200 equation were obtained by subtracting the ZHD (retrieved from the NWM) from the GPS  
201 estimated ZTD values. We estimated the precipitable water at the Hyderabad station (Figure  
202 2, lower panel), assuming the values of  $M_w$  (0.0180152 Kg/mol) and  $M_d$  (0.028964 Kg/mol).  
203  $P_w$  values were computed using value of constants given in Askne and Nordius (1987) and  
204 also following Rüeger (2002). The comparison of the results does not show any significant  
205 difference in  $P_w$  values (Figure 2, lower panel). The required mean temperature ( $T_m$ ) value  
206 was obtained from the Vienna University of Technology database  
207 (<http://ggosatm.hg.tuwien.ac.at/DELAY/ETC/TMEAN/>). The standard deviation of the  $T_m$   
208 values used in this study is 2.07 K. Accuracy of the results was tested by studying the  
209 sensitivity of  $P_w$  value to the possible error in  $T_m$  measurements.  $P_w$  values were computed  
210 for a change in  $T_m$  by 4K, 8K and 12K, and compared with the actual estimations in figure 5.  
211 Figure 5 illustrate negligible variation in  $P_w$  estimates for the above error (change) in  $T_m$ . The  
212 average difference seen for a change of 4K, 8K and 12K is 0.94 mm, 1.26 mm and 1.58 mm  
213 respectively. These differences are negligible compared to the peak  $P_w$  values approximately  
214 falling between 30 and 41 mm.

215

216 During the period between 16<sup>th</sup> October and 27<sup>th</sup> December, 2010, the ZTD values estimated  
217 at the Hyderabad GPS station vary between 2.21 and 2.53 m (Figure 2). Four major ZTD  
218 peaks, marked as HP1, HP2, HP3, and HP4 in Figure 2, with values between 2.45 m and 2.53  
219 m are visible in the ZTD time series. The ZTD is expected to be higher than the average  
220 value of 2.37 m during stormy weather conditions (Hogg et al., 1981), which however vary  
221 with altitude. Except the peak HP3, all others are observed just before or coincident with the  
222 noted atmospheric events reported from the South Indian region during the period of our  
223 study. The peak HP3 does not correspond to any abnormal atmospheric event and hence  
224 might be related to the normal water vapor accumulation process. Higher ZTD values  
225 indicate higher water vapor content in the atmosphere, which is quite clear from the PWV  
226 derived from ZTD for the same period (Figure 2). It can be seen from Figure 2 that the ZTD

227 values were high during the 18-22 October period. During this period the formation of a deep  
228 depression in the Bay of Bengal region was noticed on 19<sup>th</sup> October, which further intensified  
229 into a severe cyclonic storm (GIRI) by 22<sup>nd</sup> of October and moved towards the coast of  
230 central Myanmar and the system weakened by the end of 23<sup>rd</sup> October. Though this  
231 atmospheric system did not move towards the Indian coast, the ZTD variations observed at  
232 Hyderabad can be associated to these atmospheric events.

233

234 Under normal circumstances the accumulated water vapor gets discharged as rain at the same  
235 location. However, it is possible in the case of significant atmospheric wind conditions that  
236 the accumulated water vapor may travel to distant locations and get discharged under suitable  
237 atmospheric conditions. Such a situation could be the reason for no rainfall at Hyderabad  
238 corresponding to the higher ZTD observed during the 'GIRI' period. Significant rainfall was  
239 recorded, however, during the 'JAL' period. Similarly, the GPS derived ZTD and the derived  
240 PWV match with the rainfall that occurred at Hyderabad during the deep depression event  
241 affecting South India.

242

243 For the Tirunelveli station, the GPS derived ZTD data (Figure 3) show a comparable pattern  
244 as observed at the Hyderabad station. However, the ZTD peak values are relatively higher (>  
245 2.6 m) and show correlation with the atmospheric events noted in the South India region. No  
246 rainfall events were reported from this location during the major events GIRI and JAL. But,  
247 higher ZTD values were observed in the atmosphere during the GPS days 327 to 330 and  
248 significant amount of rain was reported from this location. The cumulative rainfall data show  
249 the slow onset of rain during 310-325 GPS days (6-21 Nov., 2010), followed by consistent  
250 and frequent rainfall during the GPS days 326-340 (22 Nov. - 06 Dec., 2010), as indicated by  
251 steep slope and the final phase of withdrawal of rain from GPS day 341 (Dec. 7) onwards  
252 depicting the decreasing trend of the monsoon pattern (e.g. Cook and Buckley, 2009). The  
253 absence of rain at this place during the GIRI and JAL period can be attributed to the possible  
254 wind pattern associated with the atmospheric events.

255 In the present study we also analyzed the ZTD variations at the IGS stations COCO and  
256 DGAR located deep inside the Indian Ocean. Table 2 gives the peak and minimum ZTD  
257 values obtained over each GPS station and help to assess the variability of the peak and  
258 minimum values of ZTD (i.e. difference in the peak ZTD values between the stations, and  
259 difference in the minimum ZTD values) between the locations. The comparison of the ZTD  
260 values of the Indian Ocean stations (COCO and DGAR) with the two inland GPS sites  
261 (HYDE and MSUN) shows the spatial variations in ZTD values. The values indicate the  
262 weakening of ZTD towards the land side. No significant changes are seen in the minimum  
263 and maximum ZTD values between the Indian Ocean locations and near the coast (Table 2).  
264 This would suggest that the effect of the events on atmospheric ZTD/PW was almost same at  
265 the interior of the ocean and on the coast. The ZTD peaks (2.75 m) and lows (2.44 to 2.46 m)  
266 observed at stations COCO and DGAR located inside the Indian Ocean are quite high when  
267 compared to an inland site, namely HYDE station, located approximately 400 km away from  
268 the East coast of India. Also, the ZTD maxima (2.53 m) and minima (2.21 m) values at  
269 HYDE are lower than the one observed for the coastal station MSUN. However, a part of the  
270 observed difference might be due to the variations in elevation between the observation  
271 points. There is a good agreement between ZTD and PWV at HYDE (Figure 2) suggesting  
272 that the increase in ZTD is due to the increase in water vapor content. This notable decrease  
273 in amplitudes of ZTD maxima and minima at the interior location indicates that stations close  
274 to the ocean or inside the ocean are more affected by the storms than stations located inland.  
275 The coastal as well as stations within the Indian Ocean islands show more peaks in the ZTD  
276 time series (Figure 3 & 4). This would probably indicate that these locations were strongly  
277 affected by the storms and depression than Hyderabad, which is located ~ 400 km inside from  
278 the East coast. The increase in ZTD may be an indication for a precursor of rain. The overall  
279 analysis shows that during the onset of a rainy day, the ZTD is significantly higher at stations  
280 MSUN, HYDE, COCO, and DGAR (Figures 2, 3, and 4). Sometimes, during rainfall, ZTD  
281 may come down if the atmosphere is not dynamic. It is difficult to predict the place of rain  
282 since atmospheric dynamics depends on various other factors, which are beyond the scope of  
283 this paper.

284

## 285 5. Conclusion

286

287 The application of GPS meteorology in identifying rapid atmospheric variations such as  
288 storms and deep depression events are evaluated in this study. The ZTD estimated from  
289 numerical weather modeling data and the ZTD computed from GPS data show quite good  
290 correspondence. The PWV derived from ZTD values and the rainfall data show a reasonable  
291 correlation at Hyderabad GPS station located well inside the Indian sub-continent. Similarly,  
292 good correlation exists between ZTD and rainfall data for the MSUN site located near the  
293 Southern coastal region of India. The calculated ZTD time series showed peaks and drops  
294 that overlap with severe atmospheric activities such as storms and deep depressions.  
295 Comparison of the ZTD values observed at different GPS stations studied indicate that the  
296 amplitudes of the ZTD values are less over the interior location as compared to the values  
297 observed at the coast and inside the Indian Ocean. GPS monitoring is an efficient and  
298 economic procedure to continuously monitor the changes in tropospheric water content and  
299 could help in identifying severe weather conditions by virtue of continuous weather data.

300

## 301 Acknowledgement

302

303 Prof. Johannes Böhm of Vienna University of Technology, Austria is thanked for his  
304 help to obtain numerical weather modeling data of the ECMWF. Vineeth K. Gahalaut  
305 extended the necessary support to carry out this study and Y. J. Bhasker Rao, Acting  
306 Director, CSIR-NGRI, given [permission to publish this work](#). We thank N. Chandrasekar for  
307 his cooperation in obtaining GPS data at M.S. University (Tirunelveli) campus. The work  
308 was carried under ILP-0301-28 (VKG).

309

310

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448 **TABLES**

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450 **Table 1:** The details of the GPS stations used in this study.

<b>Place</b>	<b>Station ID</b>	<b>Latitude (Degrees)</b>	<b>Longitude (Degrees)</b>	<b>Orthometric height (m)</b>	<b>Station details</b>
CSIR-NGRI, Hyderabad	HYDE	17.42	78.55	518.662	IGS permanent station
Cocos	COCO	-11.82	96.83	4.5928	IGS permanent station
Diego Garcia	DGAR	-6.73	73.51	11.0305	IGS permanent station
MS University, Tirunelveli	MSUN	08.76	77.65	71.0625	NGRI permanent station

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453 **Table 2:** Maximum and minimum Zenith Total Delays (ZTD) observed at the four different  
454 GPS locations.

<b>GPS station ID</b>	<b>Minimum ZTD (m)</b>	<b>Maximum ZTD (m)</b>	<b>Variability in ZTD (m)</b>
HYDE	2.21	2.53	0.32
COCO	2.44	2.75	0.31
DGAR	2.46	2.75	0.29
MSUN	2.43	2.73	0.30

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459 **Figure captions**

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461 **Figure 1:** Location of the GPS stations marked over the topographic map of South India and  
462 Northern Indian Ocean.

463 **Figure 2:** ZTD values computed from GPS data and numerical weather models for the for the  
464 Hyderabad (HYDE) station (upper panel). The lower panel shows the precipitable water  
465 vapor (PWV) estimated at the same location. PWV values were computed using value of  
466 constants given in Askne and Nordius (1987) and also following Rüeger (2002). The rainfall  
467 data are also presented and compared. The peaks in the ZTD are highlighted using ellipses  
468 and labeled as HP1 to HP4. The active periods of storms and depression are also marked.

469 **Figure 3:** ZTD values computed from GPS data for the Tirunelveli station (MSUN) (lower  
470 panel). The rainfalls reported at this location during our observation period are given using  
471 bar chart plot. Upper panel shows the cumulative rainfall data at this location.

472 **Figure 4:** ZTD values computed from GPS data and using numerical weather models are  
473 presented for two Indian Ocean GPS stations, i.e. COCO (upper panel) and DGAR (lower  
474 panel).

475 **Figure 5:** Comparison of the original PWV estimates with the values computed for possible  
476 changes/error in the determination of  $T_m$  data.

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