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1 Stress Reorientation by Earthquakes near the Ganzi-Yushu Strike- 2 Slip Fault and Interpretation with Discrete Element Modelling

3 Zhandong Su^{1, 2}, Jeoung Seok Yoon³, Arno Zang⁴, Lei Tang⁵, Hongbiao Gu¹, Chuanbing
4 Zhu⁴

5 *1 Institute of Disaster Prevention, China Earthquake Administration, Sanhe, China, 065201*

6 *2 Hebei Key Laboratory of Earthquake Disaster Prevention and Risk Assessment, Sanhe, China, 065201*

7 *3 DynaFrax UG (limited liability company), Potsdam, Germany, 14467*

8 *4 Section 2.6 Seismic Hazard and Risk Dynamics, GFZ—German Research Centre for Geosciences,
9 Telegrafenberg, Potsdam, Germany, 14473*

10 *5 Institute of Crustal Dynamics, China Earthquake Administration, Beijing, China, 100085*

11

12 **Abstract**

13 Earthquakes are generally known to alter the stress field near seismogenic faults. Observations using YRY-four-gauge borehole
14 strainmeters within Yushu (YSH) borehole near the Ganzi-Yushu fault in eastern Tibetan Plateau shows that the azimuth variation of
15 maximum horizontal stress (S_H) first decreased and then increased substantially when the earthquakes occurred during the
16 measurement period from January 1, 2009 to December 31, 2018. In this period, 38 earthquakes ($M \geq 3$) were detected near the fault
17 and the S_H orientation showed a drastic change after the 2010 M_s 7.3 Yushu mainshock. We present a discrete element modelling using
18 Particle Flow Code 2D (PFC2D) to simulate a dynamic fault rupturing process and to use the modelling results for interpretation of the
19 stress reorientation. The modelling reveals that dilatation and compression quadrants are formed around a fault rupturing in strike-
20 slip model, resulting in different spatiotemporal changes of the orientation of maximum horizontal stress ($\Delta\theta$). The value of $\Delta\theta$ in the
21 compression quadrants shows a sharp drop at the time of coseismic slip, then approaches slowly to an asymptotic value. In the
22 dilatation quadrants, $\Delta\theta$ drops by coseismic slip, then increases sharply and finally reaches a stable value. The modelled $\Delta\theta$ by coseismic
23 fault slip agrees with in-situ observations at YSH borehole during 2010 M_s 7.3 Yushu mainshock. It is also found that, the value of $\Delta\theta$
24 decreases with increasing distance from the rupturing source. We modelled the effect of fault geometry and host rock properties on the

25 $\Delta\theta$, and found that structural complexity and off-fault damage by coseismic fault slip have significant impact on the stress field
26 alteration near the rupturing source.

27

28 **Keywords** Yushu earthquakes; Ganzi-Yushu strike-slip fault; Stress reorientation; Discrete Element Modeling; Dilatation and
29 compression stress quadrants

30

31 **List of Symbols**

32 M Magnitude of earthquakes

33 M_w Moment magnitude of earthquakes

34 M_L Local magnitude of earthquakes

35 M_s Surface-wave magnitude of earthquakes

36 S_h Minimum horizontal principal stress

37 S_H Maximum horizontal principal stress

38 $\Delta\theta$ Change of the orientation of maximum horizontal stress

39 SAF San Andreas Fault

40 FGBS Four-gauge borehole strainmeter

41 φ Principal strain orientation

42 ε_1 First strain reading of FGBS

43 ε_2 Second strain reading of FGBS

44 ε_3 Third strain reading of FGBS

45 ε_4 Fourth strain reading of FGBS

46 θ_1 Azimuth of ε_1 gauge

47 YSH Yushu

48 YRY Ya Rong Yi

49	LE	Linear fault with elastic rock mass
50	LEP	Linear fault with elasto-plastic rock mass
51	CE	Curved fault with elastic rock mass
52	CEP	Curved fault with elasto-plastic rock mass
53	DEM	Distinct element method
54	$\Delta\alpha$	Rotation angle
55	δ	Stress ratio
56	σ_{xx}	Maximum normal stress
57	σ_{yy}	Minimum normal stress
58	τ_{xy}	Shear stress

59 **1 Introduction**

60 The state of the crustal stress field is of great importance for our understanding of the stability of underground
61 excavations, geodynamic processes, and seismic hazard assessment (Fuchs and Muller 2001; Hu et al. 2017;
62 Stephansson and Zang 2012; Zang and Stephansson 2010). Stress and earthquakes are generally known to be
63 interrelated; that is, stress triggers earthquakes and earthquakes, in turn, alter the stress state on surrounding faults
64 (Agnès et al. 2005; Hardebeck 2004; Harris 1998; Kilb et al. 2000; Lin et al. 2007; Reasenber and Simpson 1992;
65 Stein et al. 2010; Stein 2000). The earthquake-induced stress changes, i.e., stress rotations, are commonly used in
66 characterizing the evolution of post-seismic stress and understanding the earthquake-stress interaction and the
67 reloading of faults (Hardebeck and Okada 2018).

68 The rotation of the S_H has been investigated based on the inversion of focal mechanisms along the strike-slip
69 fault ruptures. For instance, Hauksson (1994) concluded that S_H rotated 5°-24° clockwise during the M_w 6.1 Joshua
70 Tree earthquake and flipped back to the pre-Joshua Tree orientation state when the M_w 7.3 Landers mainshock

71 occurred. Zhao et al. (1997) derived a counterclockwise rotation of principal stress axis of ca. 20° at the time of the
72 M_w 6.7 Northridge earthquake and a slow return to the original state. Ratchkovski (2003) demonstrated that the
73 principal stress axis rotated $\sim 20^\circ$ in the vicinity of the 2002 M_w 7.9 earthquake mainshock hypocenter relative to
74 the strike-slip Denali fault. Bohnhoff (2006) investigated the stress reorientation due to the 1999 M_w 7.4 Izmit main
75 earthquake and the aftershock along the right-lateral slip striking EW using 446 fault plane solutions. He concluded
76 that the maximum horizontal compressive stress axis rotated anti-clockwise 8° in the Izmit-Sapanca area whereas
77 it rotated clockwise towards the eastern end of the rupture. Yoshida et al. (2014) have investigated the stress field
78 regarding the 2008 M 7.2 Iwate-Miyagi Nairiku earthquake in NE Japan, and found the maximum principal stress
79 axes differ remarkably before and after the main shock. Stress rotations were also examined during the 2016 M 7.3
80 Kumamoto earthquake along the Futagawa-Hinagu fault zone, that is, the minimum principal stress axes in
81 the vicinity of the fault plane significantly rotated counterclockwise after the M 6.5 foreshock and rotated clockwise
82 after the M 7.3 main shock in the Hinagu fault segment (Yoshida et al., 2016b; Yu et al., 2019). However, the stress
83 changes based on focal mechanism inversion along strike-slip faults are predominately shown as an overall pattern
84 irrespective of individual stress variation related to fault segments.

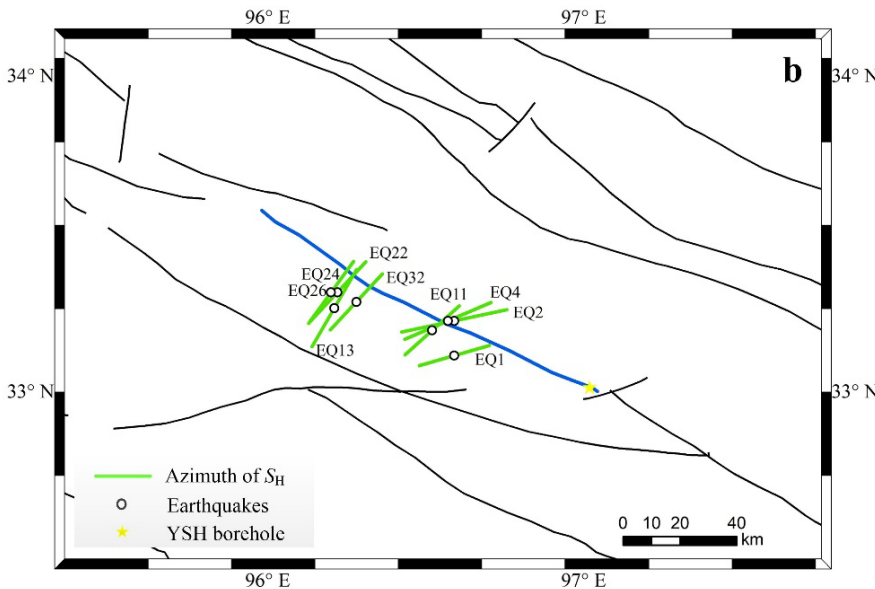
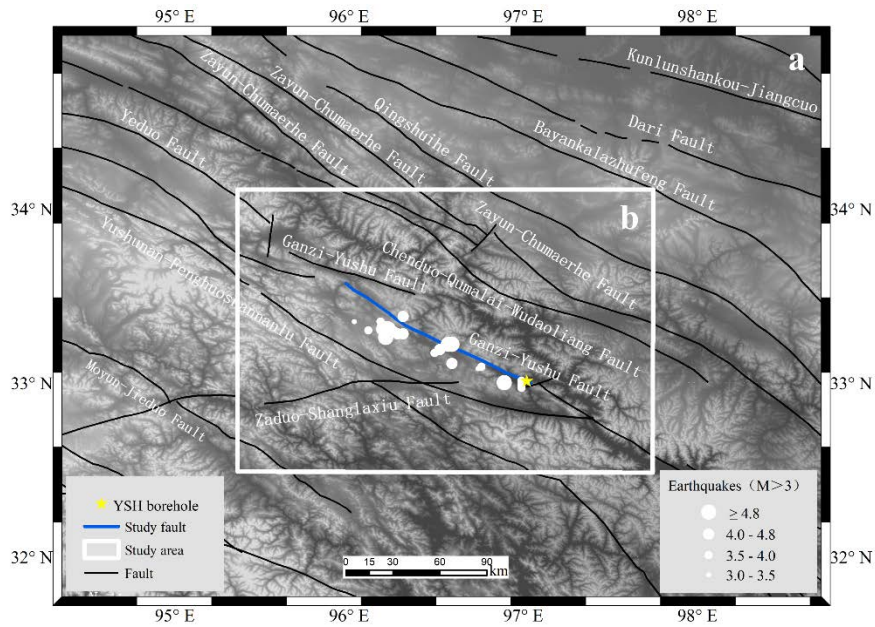
85 In-situ stress measurements provide also information on stress reorientation pattern from the upper plate. It is
86 known that localized stress rotations measured and detected in the vicinity of faults penetrated by boreholes reveal
87 that this reorientation phenomenon is associated with the slip motion of pre-existing active faults (Barton and
88 Zoback 1994; Kerkela and Stock 1996; Paillet and Kim 1987; Shamir and Zoback 1992). The orientation of S_H
89 measured far away from the San Andreas Fault (SAF) is NNE. However, the azimuth of the S_H measured near the
90 fault approximately rotates to EW or NW (Sbar et al. 1979), perpendicular to the strike of the SAF in its immediate
91 vicinity. Such spatial variations were also observed to be markedly associated with plate movement (Fuchs and
92 Muller 2001). However, the stress rotations observed locally at several wellbores were presented, and fewer efforts
93 have been made tracing the dynamic variation of S_H within or near the borehole, and investigating the overall stress
94 reorientation pattern along a segmented strike-slip fault.

95 Hence, our study objective is mainly focused on the temporal and spatial variation patterns of S_H along the Ganzi-
96 Yushu strike-slip fault during earthquake occurrence and understanding the physics behind this phenomenon by
97 numerical modeling. A systematic investigation of the impact of fault geometry (linear fault and curved-segmented
98 fault) and rock properties (elastic and elasto-plastic) on the spatiotemporal changes in the stress orientation around
99 the Ganzi-Yushu fault rupture is performed numerically.

100 **2 Tectonic setting**

101 The study region is located in a high mountain region along the Ganzi-Yushu fault zone in central-eastern Tibet,
102 China (Fig. 1). The Ganzi-Yushu Fault is part of the Xianshuihe Fault system (Shifeng et al. 2008). Based on the
103 inversion of the seismic focal mechanism, the Ganzi-Yushu fault zone exhibits approximately left-lateral slip on a
104 sub-vertical plane striking WNW-ESE. This is in response to the eastward extrusion and northeastward shortening
105 of the central Tibetan Plateau due to the continuing collision of the Indian Plate and the Eurasian Plate. On April
106 14, 2010, an M_w 6.9 earthquake occurred on the Ganzi-Yushu fault and resulted in widespread damage (Tobita et
107 al. 2011). There are 38 aftershocks with $M > 3$ which occurred within the study region including seven aftershocks
108 with $M > 4.8$ (Table 1 and Fig. 1b). Field investigations show that the Yushu earthquake produced a surface rupture
109 zone more than 30 km long with a maximum left-lateral displacement of 3.2 meter in the central part of the Yushu
110 rupture (Lin et al. 2011b). In 1738, an M 7.5 event located in the vicinity of the 2010 event is reported (Lin et al.
111 2011a). Along the Ganzi-Yushu fault, the total average left-lateral slip-rate has been estimated to be more than 10
112 mm/a (Wang et al. 2001; Wen et al. 2003). The slip deformation and seismicity data show that the Ganzi-Yushu
113 fault zone is currently active as a seismogenic fault that triggers large-magnitude earthquakes.

114



115

116

117 **Fig. 1** (a) Color-shaded relief map modified from GDEMDEM 30m data (the data set is provided by Geospatial Data Cloud
 118 site, Computer Network Information Center, Chinese Academy of Sciences) showing the topographic and tectonic setting of
 119 the study area (white rectangle). The blue solid line denotes the study fault (Ganzi-Yushu fault) and the black solid lines denote
 120 the faults near the study fault. The location of the YSH borehole is remarked as the yellow star used for monitoring the strain
 121 variation continuously by minutes and hours. There are 38 earthquakes indicated by the white dots with magnitudes ranging
 122 from M 3.0 to M 7.3 that occurred between January 1, 2009 and December 31, 2018 (Table 1). (b) Zoomed map of the study
 123 area. The green bars indicate the azimuth of the S_H inverted by the focal mechanism of $M_s \geq 4.8$ earthquakes (except for EQ3)
 124 during the abovementioned period. The bar lengths are proportional to the earthquake magnitudes.

125

126 **Table 1** Earthquakes ($M \geq 3$) occurring between 1 January 2009 and 31 December 2018 near the Ganzi-Yushu fault (The data
 127 are provided by the China Earthquake Data Center) and the azimuth of S_H , computed based on focal mechanism data from the
 128 CMT catalog (Ekström et al. 2012).

No.	Time	Long.	Lat.	Depth	Magnitude	Azimuth of S_H (°)
-----	------	-------	------	-------	-----------	----------------------

		/ °E	/ °N	/km		
EQ1	14/04/2010 05:39:58	96.59	33.11	15	M_s 4.8	74
EQ2	14/04/2010 07:49:36	96.59	33.22	14	M_s 7.3	78
EQ3	14/04/2010 08:01:15	96.89	33.00	6	M_s 4.9	
EQ4	14/04/2010 09:25:16	96.57	33.22	17	M_s 6.4	67
EQ5	14/04/2010 20:19:30	96.99	32.97	10	M_L 3.7	
EQ6	15/04/2010 12:00:06	96.99	33.01	10	M_L 3.6	
EQ7	16/04/2010 02:30:17	96.76	33.09	10	M_L 3.7	
EQ8	16/04/2010 06:37:07	96.98	32.99	10	M_L 3.2	
EQ9	17/04/2010 07:04:12	96.49	33.17	7	M_s 3.6	
EQ10	21/04/2010 04:23:38	96.74	33.08	10	M_L 3.2	
EQ11	29/04/2010 00:48:36	96.52	33.19	10	M_L 4.6	48
EQ12	29/04/2010 00:53:52	96.52	33.21	4	M_L 3.4	
EQ13	29/05/2010 10:29:49	96.21	33.26	10	M_s 5.9	30
EQ14	29/05/2010 09:36:00	96.24	33.28	7	M_L 3.2	
EQ15	29/05/2010 10:43:53	96.22	33.31	9	M_L 3.8	
EQ16	29/05/2010 10:45:26	96.22	33.31	10	M_L 3.3	
EQ17	29/05/2010 10:46:53	96.20	33.32	5	M_L 3.4	
EQ18	29/05/2010 11:11:16	96.18	33.30	10	M_s 4.0	
EQ19	01/06/2010 09:41:03	96.18	33.29	9	M_s 3.2	
EQ20	02/06/2010 10:36:24	96.23	33.27	10	M_L 3.3	
EQ21	03/06/2010 13:06:19	96.20	33.34	8	M_L 3.3	
EQ22	03/06/2010 13:35:42	96.22	33.31	11	M_s 5.4	43
EQ23	03/06/2010 13:46:57	96.31	33.28	10	M_s 4.3	
EQ24	04/06/2010 04:47:04	96.20	33.31	7	M_s 5.0	36
EQ25	04/06/2010 10:00:45	96.11	33.30	4	M_s 3.7	

EQ26	07/06/2010 00:42:42	96.20	33.31	10	M_s 4.8	36
EQ27	07/06/2010 01:28:29	96.24	33.32	6	M_s 3.7	
EQ28	07/06/2010 01:28:29	96.20	33.29	10	M_s 4.0	
EQ29	10/06/2010 02:31:27	96.18	33.33	9	M_s 3.3	
EQ30	15/06/2010 16:08:30	96.31	33.38	6	M_s 4.4	
EQ31	18/06/2010 22:10:16	96.20	33.32	10	M_s 3.4	
EQ32	08/09/2010 04:50:59	96.28	33.28	30	M_s 4.8	43
EQ33	08/09/2010 09:58:08	96.26	33.30	10	M_L 3.7	
EQ34	04/10/2010 15:58:28	96.20	33.31	10	M_L 3.0	
EQ35	27/11/2010 07:07:02	96.03	33.35	10	M_L 3.2	
EQ36	07/08/2014 18:28:39	96.60	33.18	7	M_s 3.7	
EQ37	13/06/2015 13:14:28	96.56	33.23	10	M_s 3.5	
EQ38	01/11/2017 13:33:38	96.18	33.35	9	M_s 4.0	

129

130 **3 Observation method and data**

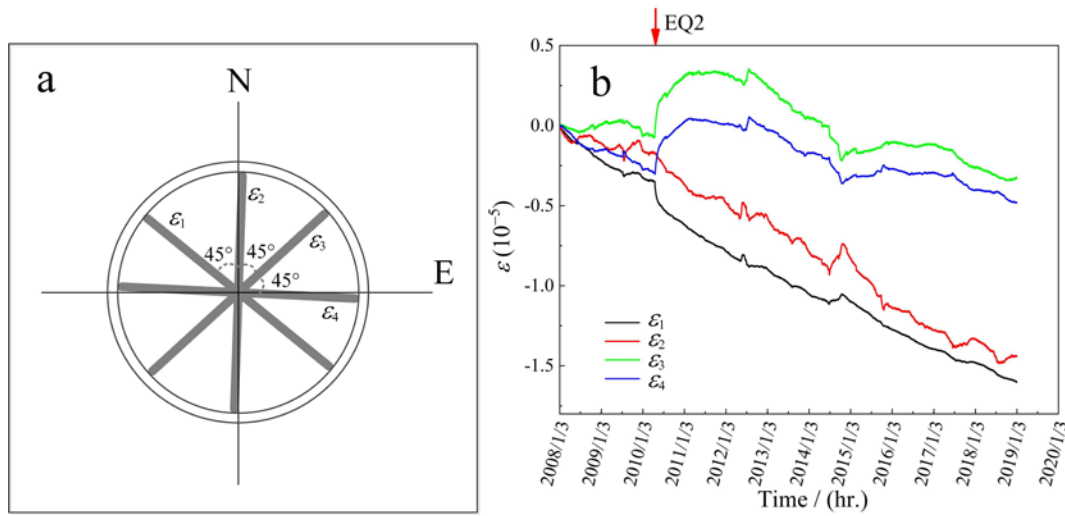
131 YRY-4-type four-gauge borehole strainmeters (FGBS) manufactured by Chi et al. (2009) have been largely
132 deployed by China Earthquake Administration to monitor the temporal changes in horizontal strain in response to
133 the U.S. Plate Boundary Observatory project. There are approximately 40 YRY-4-type FGBS stations in China where
134 data can be monitored with sampling rates of one per minute or one data point per hour (Qiu et al. 2013). The data
135 obtained from these borehole strainmeters have been used in many scientific studies (Qiu and Shi 2004; Qiu et al.
136 2007, 2011). We selected one of these stations, namely the YSH borehole, which was located close to the Yushu
137 earthquake epicenter and approximately 80 meters north from the Ganzi-Yushu fault (Fig. 1) to analyse strain data
138 in parallel with aftershock sequences. In this way, strain variation in relation to the earthquake preparation process
139 can be investigated (Qiu et al. 2011). Since the YSH borehole strainmeter has been in operation since January 3,
140 2008, strain (ϵ) variation associated with the Yushu earthquake which occurred on April 14, 2010 can be

141 investigated (Fig. 2b). The YSH borehole strainmeter was installed at a depth of 39.5 m with four-component gauges
 142 that are horizontally emplaced with 45-degree angles, to measure strain changes in borehole diameter with sampling
 143 rates of one data point per minute and one per hour (Fig. 2a). The depth was selected due to the theoretical model
 144 used to derive strain values assuming that the vertical normal stress is zero (Qiu et al. 2013). Based on the measured
 145 strain data, the principal strain orientation (φ) was derived as (Qiu et al. 2013)

$$146 \quad \square \quad \varphi = \frac{1}{2} \arctan \left(\frac{\varepsilon_2 - \varepsilon_4}{\varepsilon_1 - \varepsilon_3} \right) + \theta_1 \quad (1)$$

147 where ε_i ($i = 1, 2, 3, 4$) are the measurements by the four gauges installed in the borehole and θ_1 is the azimuth of ε_1
 148 gauge. We assumed that the orientation of S_H corresponds to φ , taking into consideration that the elastic modulus
 149 of the rock mass remains constant, as the YSH borehole strainmeter was installed in intact granite rock.

150



151

152 **Fig. 2** (a) Alignment of the gauges (grey bars) for strain measurement in the YSH borehole; (b) Temporal
 153 (hourly-based) changes in the strain (ε) from January 3, 2008 to December 31, 2018 in YSH borehole. The red
 154 arrow on the top indicates the time of the Yushu mainshock (M_s 7.3 see Table 1).

155

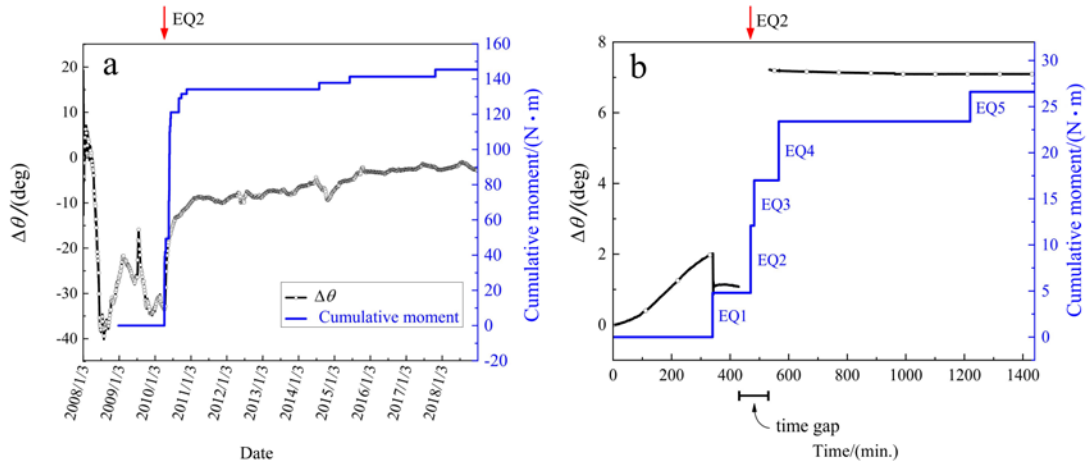
156 To analyze the relationship between the reorientation of S_H and the occurrence of the earthquake involving the
 157 Ganzi-Yushu strike-slip fault, we present the change of the orientation $\Delta\theta$ of S_H and the cumulative magnitude (M_s)
 158 of earthquakes from January 3, 2008 to December 31, 2018 (Fig. 3). We convert local magnitude M_L in Table 1 to
 159 surface-wave magnitude M_S using the empirical relationship given as (Gutenberg and Richter 1956)

$$M_s = 1.27(M_L - 1) - 0.016M_L^2 \quad (2)$$

160

161 The value of $\Delta\theta$ increases substantially from approximately -33 degrees to -11 degrees, more than 20 degrees, while
 162 the cumulative M_s increases by about 134 N·m from April 14, 2010 to November 27, 2010 (Fig. 3a). This implies
 163 that the S_H axis observed in the YSH borehole rotated 22 degrees clockwise. If we zoom into the variation of data
 164 sampled per minute on the day the Yushu earthquake (EQ2) occurred, $\Delta\theta$ first decreases by about 1 degree and then
 165 increases by 6 degrees, while the cumulative M_s increases by 23 N·m in the same time period (Fig. 3b). Although
 166 the co-seismic data were not recorded because of broken power supply by earthquake interruption (Fig. 3b, gap in
 167 data), the final $\Delta\theta$ was about 5 degrees from the original state.

168



169

170 **Fig. 3** The $\Delta\theta$ and the cumulative magnitude of earthquakes occurring near the Ganzi-Yushu fault vs. monitoring date from 3
 171 January 2008 to 31 December 2018 with a sampling rate of per hour (a). The zoomed time window sampling rate of per minute
 172 on the day of the Yushu mainshock occurring on 14 April 2010 (b). The black bar below shows the gap (103 minutes) in data
 173 due to the broken power supply by earthquake interruption. The red arrow on the top indicates the time of the Yushu mainshock.

174

175 4 Numerical model and methodology

176 4.1 Particle Flow Code 2D

177 For numerical modelling of stress evolution around a seismogenic fault associated with its dynamic rupture, we
 178 used Particle Flow Code 2D v4 (PFC2D v4) which is a commercial software of Itasca Consulting Group (Itasca 2008)
 179 developed on the basis of Discrete/Distinct Element Method, DEM (Cundall 1971; Cundall and Strack 1979). The

180 concept of DEM is implemented in PFC and the way in which PFC is applied for simulation of rock mechanics
181 problems is referred to as Bonded Particle Modelling (BPM, Potyondy and Cundall 2004). PFC has been, since its
182 release in late 1990s, applied to rock mechanics and rock engineering problems due to its strong advantage that
183 modelling of a system with large populations of particles require only modest amounts of computer memory and
184 physical instability (large deformation problems, e.g. landslide, rock blasting, rock fall) can be modelled without
185 numerical difficulty. Further details on BPM application in rock mechanics problems can be found in Potyondy and
186 Cundall (2004).

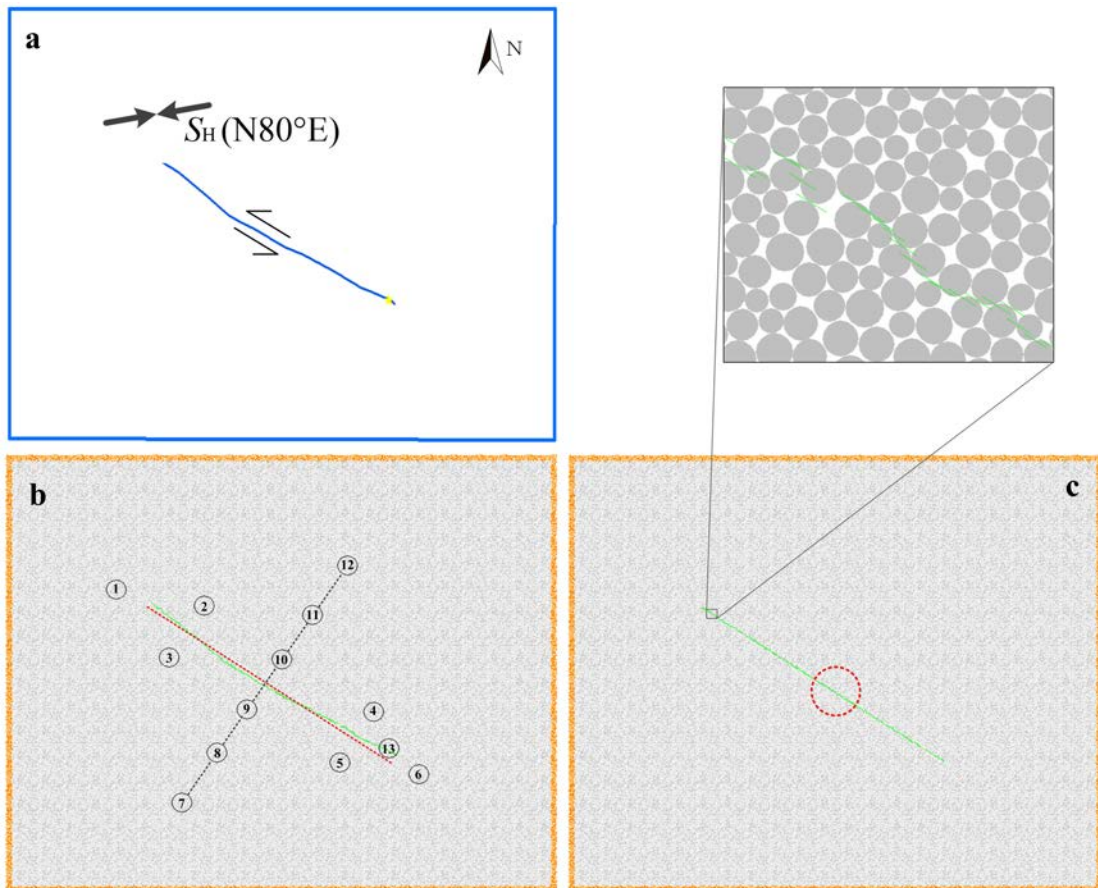
187 Lately, the BPM method has evolved significantly by implementation of hydro-mechanical (HM) and thermo-
188 mechanical (TM) coupling concepts. For HM coupling, PFC has been applied widely for simulation of fluid injection
189 induced seismicity in the fields of deep geothermal energy (Hazzard et al. 2002; Hofmann et al. 2016a; Yoon et al.
190 2014b, 2015a), shale gas hydraulic fracturing (Al-Busaidi et al. 2005; Hofmann et al. 2016b), and waste water
191 disposal (Yoon et al. 2015b). For TM coupling, PFC has been applied to geological disposal of spent nuclear fuel and
192 radioactive wastes (Yoon et al. 2016; Yoon and Zang 2019).

193

194 **4.2 Modelling of fault dynamic rupture**

195 Using PFC2D, we generated a geological model representing the Ganzi-Yushu site as shown in Fig. 1. The model
196 size is $220 \times 180 \text{ km}^2$ (Fig. 4a), and the areal space is packed with 388,987 disks with diameters ranging between
197 130 m to 215 m (Fig. 4b). To investigate the temporal and spatial variation patterns of S_H along the study fault, we
198 set measurement circles in the moving direction (Fig. 4b, stress circles (2) and (5)), opposite moving direction (Fig.
199 4b, stress circles (3) and (4)), and tip of the fault (Fig. 4b, stress circles (1) and (6)); we set 6 measurement circles
200 symmetrically lay on the perpendicular profile line in the middle of the fault (Fig. 4b, stress circles (7) to (12)) and
201 one measurement circle at the YSH borehole position (Fig. 4b, stress circles (13)). To systematically investigate the
202 effect of the fault geometry (e.g., linear fault and curved fault) and the effect of off-fault host rock damage on the
203 stress reorientation, we setup four scenarios of fault dynamic rupture: 1) linear fault with elastic rock mass (LE); 2)

204 linear fault with elasto-plastic rock mass (LEP); 3) curved fault with elastic rock mass (CE) and 4) curved fault with
 205 elasto-plastic rock mass (CEP). We used enhanced parallel bond model (Yoon et al., 2014b) and smooth joint contact
 206 model (Ivars et al. 2011) for the host rock and the (segmented) fault system, respectively. The failure of the parallel
 207 bond and the smooth joint contact is governed by the Mohr-Coulomb failure criterion of which the parameters are
 208 listed in Table 2.



209 **Fig. 4** a) Geometry of the investigated Ganzi-Yushu fault. The yellow star marks the location of the observation borehole. b)
 210 Particle curved fault model with monitoring stress circles (radius = 4000 m). Circle (13) is located exactly at the borehole
 211 position. The circles (7) to (12) lay on the perpendicular profile line (black dotted line). The red dotted line indicates the linear
 212 fault geometry applied in the numerical modelling. c) Particle linear fault model with measurement circle indicated by red
 213 dotted circle for converging to target stress values. The green curve and green line represent the curved fault (b) and linear fault
 214 respectively.

215
 216
 217 To mimic a fault dynamic rupture, we used the modelling approach as described in Yoon et al. (2017). The
 218 approach for simulating a dynamic fault rupture first starts with locking the fault by strengthening the smooth joint
 219 bond strength (tensile and cohesion). Second, the model is compressed by servo-controlling the velocities of the

220 boundary layer particles (orange colored in Fig. 4b). The servo-control process continues until stress components
221 (σ_{xx} , τ_{xy} , σ_{yy}) that are monitored in the stress measurement circle (Fig. 4c) located at the model center reach the
222 target stress magnitudes and orientations. We assumed that the 2D model section is located at depth of 2000 m,
223 and therefore, the stresses in situ are 64 MPa and 38 MPa for the maximum and minimum horizontal stress S_H and
224 S_h , respectively. The stress magnitudes (in MPa) are calculated by the following equations based on the in-situ stress
225 measurements in Qinghai Tibet block, China (Yang 2013),

$$226 \quad S_H = 0.0292Z + 5.185 \quad (3)$$

$$227 \quad S_h = 0.0172Z + 3.681 \quad (4)$$

228 where, Z is the depth (m).

229 The stress orientation applied here is mainly based on the Global Positioning System (GPS) velocity field near
230 the study region, and the average direction of the GPS velocity determined by seven stations within the study region
231 shows an angle anticlockwise about 10° to the horizontal axis (E-W), which indicates that the orientation of in-situ
232 S_H is nearly $N80^\circ E$ (Zheng et al. 2017). To simulate the 10° deviation of the in-situ S_H orientation from the horizontal
233 axis, the velocities of the boundary layer particles (Fig. 4b, orange colored) are servo-controlled so that shear stress
234 develops within the stress measurement circle at the model center (Fig. 4c). The resulting principal stresses
235 therefore deviates 10° from the model axes. The magnitudes of the in-situ stress components, i.e., normal stresses
236 (σ_{xx} and σ_{yy}) and shear stress (τ_{xy}) to be used for servo-controlling the velocities of the boundary layer particles, in
237 the stress measurement circle at the model center are determined by Mohr circle stress analysis (for details, we refer
238 to Yoon et al., 2014a).

239 In a third step, dynamic faulting was simulated by unlocking the fault. The strained fault was unlocked by
240 instantaneous reduction of the particle bond strength mimicking dynamic fault rupture and energy release. Upon
241 fault unlock, a seismic wave generates, propagates, and attenuates due to damping. The local damping coefficient
242 of 0.7 is applied to particles to mimic attenuation of seismic energy that propagates in a form of a seismic wave
243 generated at the seismic source (rupturing fault). In future study, spatial variation of the damping coefficient will

244 be considered by taking into account the site-specific geological heterogeneity conditions. This approach of
 245 simulating fault dynamic rupture by unlocking the fault strength and stiffness is similar to the modelling approach
 246 by Bilham and King (1989), Saucier et al. (1992) and Fälth et al. (2015). Additionally, the friction coefficient, friction
 247 angle and dilation angle of the smooth joints, listed in Table 2, are lowered to 10% of their initial values, taking into
 248 account the fault asperity loss by dynamic rupture (Yoon et al., 2017).

249

250 **Table 2** Modelling properties of the rock mass and the Ganzi-Yushu fault.

Parameters	Value	References
<i>Rock mass by parallel bond model</i>		
Density	2720 kg/m ³	Yang (2013)
Poisson's ratio	0.25	Yuan (2017)
Elastic modulus	70 GPa	Yuan (2017)
Friction angle	50 °	
Cohesion	30 MPa	
Tensile strength	10 MPa	
<i>Fault by smooth joint model</i>		
Normal stiffness	600 GPa/m	
Shear stiffness	50 GPa/m	
Friction coefficient	0.2	
Tensile strength	0.2 MPa	
Cohesion	1 MPa	
Friction angle	30 °	
Dilation angle	3 °	

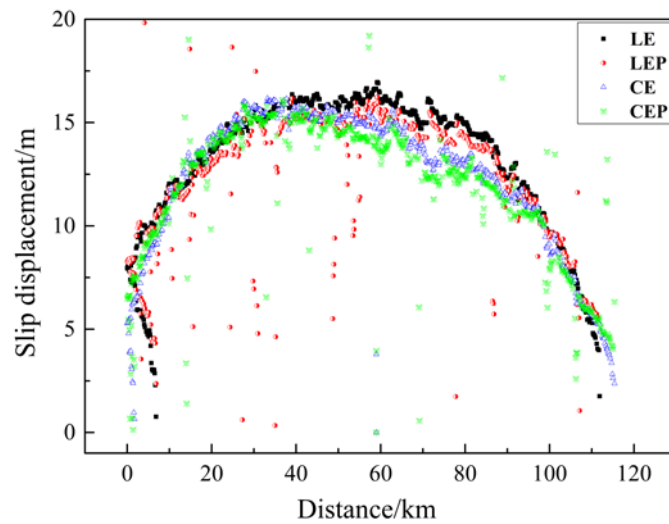
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253

254 **5 Results**

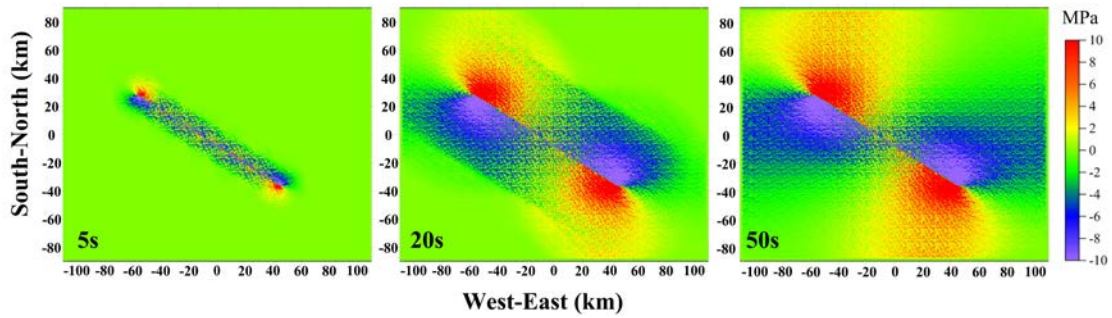
255 Fig. 5 shows the fault slip displacement shortly (90 seconds) after rupture initiation for each scenario. Slip
256 displacements of LEP and CEP scenarios are lower compared to the corresponding elastic host rock scenarios (LE,
257 CE). The difference is due to the off-fault damage, where the co-seismically-generated dynamic energy is consumed,
258 resulting in less slip along the fault trace as compared with the elastic host rock scenario. The linear fault model
259 shows a parabolic profile of co-seismic slip displacement versus fault length, whereas the curved fault model shows
260 an asymmetric slip distribution, which reasonably well follows the slip profiles observed along natural earthquake
261 faults (Manighetti et al. 2005, 2007, 2009).



262 **Fig. 5** Co-seismic slip distribution of the fault trace embedded in the elastic and elasto-plastic host rock masses at 90 seconds
263 after rupture initiation. The coordinate origin is the left tip of the fault trace.
264

265

266 The evolution of the stress quadrants is illustrated in Fig. 6. When the northeastern block of the fault slips NE,
267 the stress in the moving direction will increase, resulting in a compressive stress increase (compression quadrant).
268 The force in the opposite direction will drop, resulting in a tensile stress increase (dilatation quadrant). The
269 evolution of the compression and dilatation quadrants with respect to the other three scenarios (LEP, CE and CEP)
270 is similar as shown in the supplementary material, see Online Resource 1.



271

272 **Fig. 6** Spatiotemporal evolution of compression (red) and dilatation (blue) stress quadrants for the LI scenario.

273

274 As can be clearly seen from Fig. 7, the $\Delta\theta$ variation for the four scenarios typically show different patterns.

275 However, no obvious changes in $\Delta\theta$ could be observed in response to the strain energy release after approximately

276 50 s. The $\Delta\theta$ measured in the compression quadrants for each scenario drops substantially from approximately 0°

277 to -10° , exhibiting approximately 10° counterclockwise rotation (Fig. 7, stress circles (2) and (5)). The azimuth

278 change over time for elasto-plastic rock mass shows some undulations, mainly due to off-fault damage (Xu and

279 Arson 2015), seen in Fig. 8b. The undulations in the initial part of the curve may be due to dynamic effect, where

280 the stress at the location is affected by the dynamic wave passing by (Belardinelli et al. 1999). However, the

281 asymptotic values at $t > 50$ s are similar to the corresponding values of faults with elastic rock mass. The curved

282 faults show larger $\Delta\theta$ values than the linear faults. This indicates that the curvature of the fault has a more significant

283 impact on S_H rotation than the host rock properties.

284 The $\Delta\theta$ values measured in the dilatation quadrants for each scenario show first a sharp decrease with

285 subsequent increases to a stable value corresponding to the starting value (Fig. 7, stress circles (3) and (4)). This

286 indicates that the stress azimuth rotates back to the original state after the earthquake occurred in the dilatation

287 quadrants. The LE scenario shows the largest negative variation value, reaching more than -8° while the CE scenario

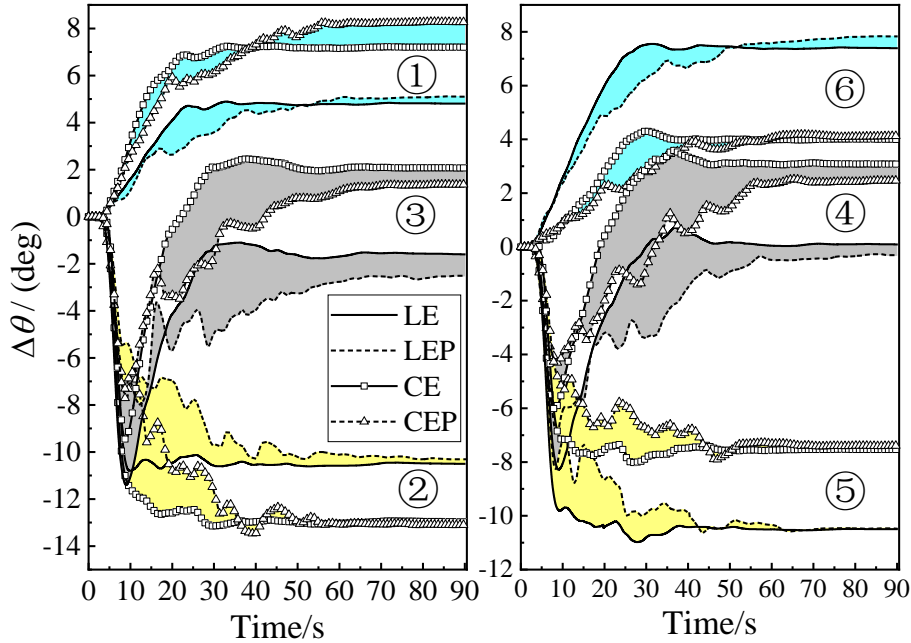
288 shows the largest positive variation value (Fig. 7, stress circles (3) and (4)). Though the azimuth for each scenario

289 increases to a stable value, only the scenarios regarding curved faults, i.e., CE and CEP result in a positive value.

290 This implies that only the azimuth of S_H for the CE and CEP scenarios increase after the earthquake compared to

291 the other scenarios (Fig. 7, stress circles (3) and (4)). The asymptotic values of stress azimuth at times larger than

292 50 s for elasto-plastic rock mass are less by about one degree than the asymptotic values for stress azimuth for elastic
 293 rock mass. This may be due to lower tensional force caused by the off-fault damage in CEP scenario (Fig. 8b) as
 294 compared to the CE scenario (Fig. 8a).



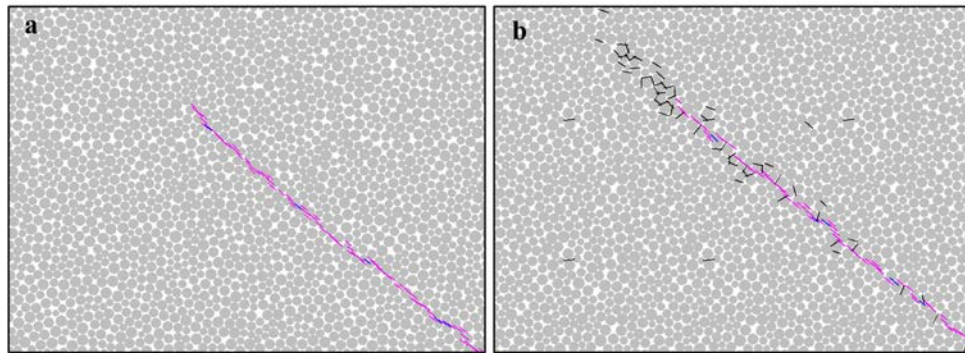
295

296 **Fig. 7** Temporal changes of $\Delta\theta$ for each scenario. The stress variation observed at the tip of the fault (stress circles (1) and (6))
 297 indicated by cyan region. The stress variation observed in the compression quadrants (stress circles (2) and (5)) indicated by
 298 yellow region. The stress variation observed in the dilatation quadrants (stress circles (3) and (4)) indicated by grey region.

299

300 The $\Delta\theta$ values measured at the tip of the fault for the four scenarios increases substantially and subsequent
 301 approaches a nearly constant plateau value. However, the maximum $\Delta\theta$ value for the curved faults (CE and CEP)
 302 measured at the northwest tip of the fault is approximately two times larger than that at the southeast tip of the fault
 303 (Fig. 7, stress circles (1) and (6), refer to Fig. 4b for the measurement circle locations), which is probably due to the
 304 curved geometry of the fault. As can be clearly seen from Fig. 4b, due to the bending effect of the curved fault, the
 305 measurement circle (1) located at the northwest tip of the fault is mostly within the dilatation quadrants, while the
 306 measurement circle (6) located at the southeast tip of the fault is mostly within the compression quadrants. As
 307 illustrated above, the maximum $\Delta\theta$ value finally increases within dilatation quadrants as compared to the decrease
 308 within compression quadrants. The stress change is therefore asymmetric, i.e. it is larger at one end of the curved
 309 fault as compared with the other end.

310

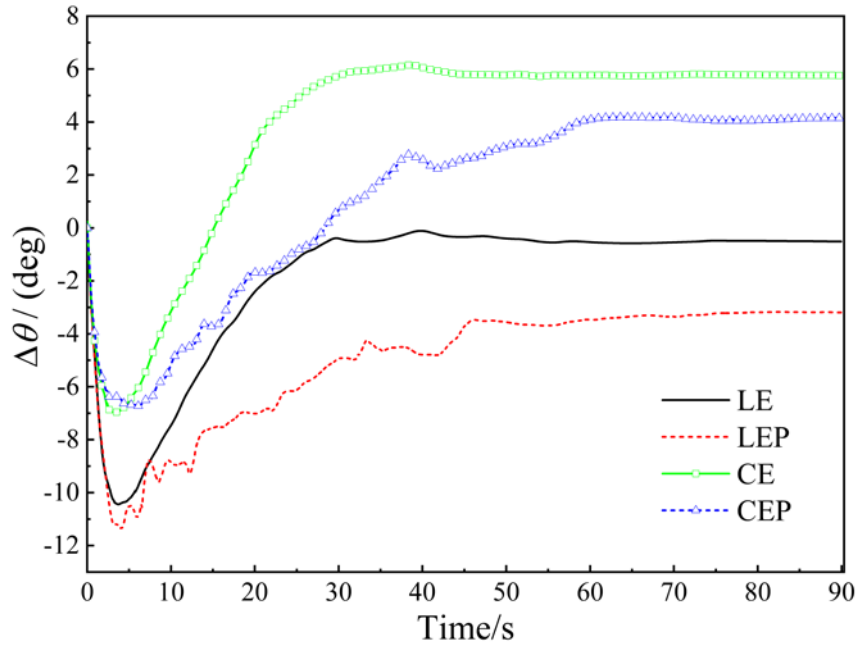


311

312 **Fig. 8** Close-up view of cracking (smooth joints in magenta and blue) after earthquake in CE scenario (a) and
313 in CEP scenario (b). The black bar indicates the off-fault damage.

314

315 Fig. 9 shows the developments of $\Delta\theta$ for four scenarios measured in the measurement circle (13). First, the
316 orientation values drop significantly, and then increase to a stable value, which are consistent with those measured
317 in the dilatation quadrants (Fig. 7, measurement circles (3) and (4)). Note that the maximum positive magnitudes
318 of $\Delta\theta$ for each scenario measured in the measurement circle (13) are larger than that measured in the measurement
319 circle (4) presumably due to the position near to the fault, i.e., the approximate distance is 80 m from the YSH
320 borehole to the fault. In comparison to the field observation presented in Fig.3b, the magnitude of $\Delta\theta$ first decreases
321 by about 6 degrees and then increases by 10 degrees for the CEP scenario within 50 s. It seems that the initial drop
322 in model is much larger than that in borehole observations. The reason for this difference is possibly due to the fact
323 that we assume the fault rupture hypocenter is at the depth of the stress measurement circle (2D plane), whereas
324 the Yushu earthquake hypocenter is at larger depth and the strain measurement was done at shallow depth.
325 Therefore, the distance between the EQ hypocenter and the gauge measurement is relatively large in nature and
326 relatively small in the model, which may explain the larger initial stress drop in the model. In addition, the field data
327 were recorded with sampling rates of one per minute (Fig.3b), and unfortunately, we cannot resolve co-seismic
328 strain data during the occurrence of EQ2. If we cumulatively add the energy of four events (EQ1, EQ2, EQ3 and EQ4)
329 in one time step of strain energy release, the $\Delta\theta$ variation modeled during the activation process of the smooth joints
330 agrees with in-situ observations in the YSH borehole.



331

332 **Fig. 9** Temporal changes of $\Delta\theta$ for each model scenario at the location of the YSH measuring borehole (stress circle (13)).

333

334 In Fig. 10, we shift the focus to the maximum values of $\Delta\theta$ as a function of distance perpendicular to the fault.

335 The maximum $\Delta\theta$ variation trend for all four scenarios is almost similar; that is, the largest $\Delta\theta$ value occurs near the

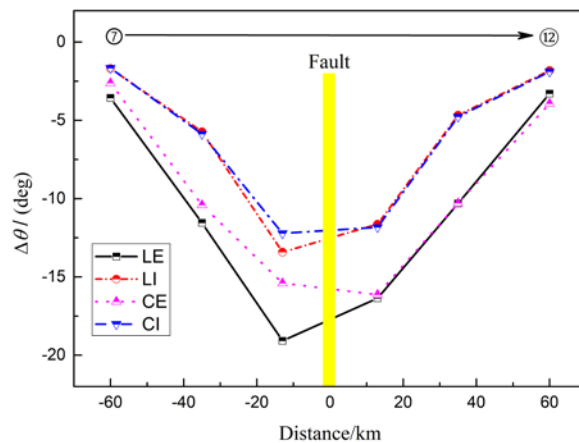
336 fault, and it drops as the distance increases from the fault. The maximum $\Delta\theta$ variations for linear faults (e.g., LE and

337 LEP), which are not symmetric to the fault, are likely attributed to the location of the fault in the model. We conclude

338 that the further the measurement distance is from the fault, the smaller the magnitudes of maximum $\Delta\theta$ are, i.e., at

339 50 m distance from fault core, the mean maximum $\Delta\theta$ drops by 81%, 86%, 79% and 85% with distance from the

340 fault for scenarios LE, LEP, CE and CEP, respectively (Fig. 10).



341

342 **Fig. 10** Maximum $\Delta\theta$ vs. distance from the fault on the perpendicular profile line (stress circles (7) to (12)).

343 **6 Discussion**

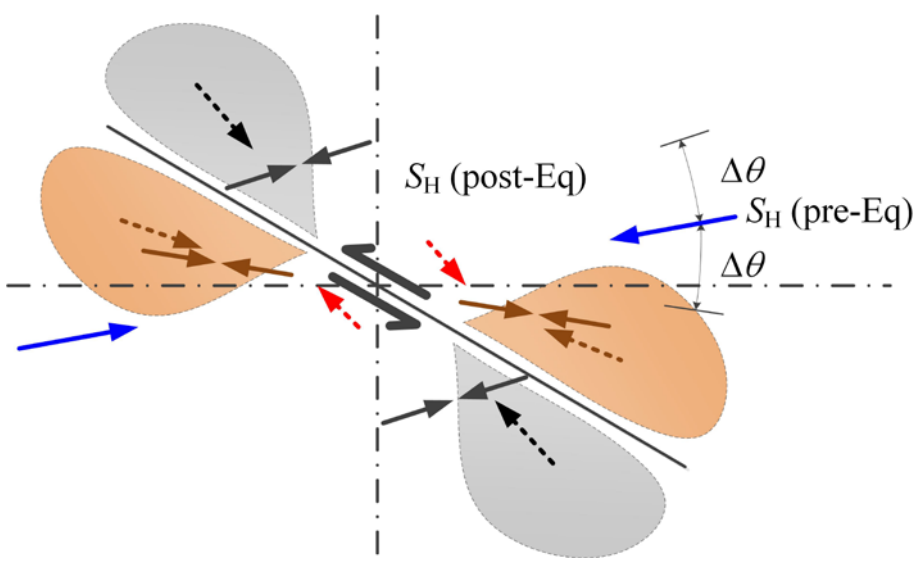
344 We mainly focused on numerical modelling of reproducing such spatio-temporal changes in the orientation of
345 local maximum horizontal stress at several locations along the trace of a rupturing fault. The effects of fault geometry
346 and off-fault damage were investigated with discrete element numerical simulations using a single and segmented
347 fault surrounded by elastic and elasto-plastic host rock. By comparing a unique (although not continuous) field data
348 set recorded by a borehole strain meter close to a pure strike-slip fault, we developed a synoptic geomechanical
349 model for the stress redistribution in such a situation. We found that the $\Delta\theta$ values observed in the YSH borehole
350 near the Ganzi-Yushu fault first decreases and then increases substantially with increasing cumulative magnitude
351 of earthquakes occurring near the Ganzi-Yushu fault. The dilatation and compression stress quadrants can be
352 gradually formed along the strike-slip fault after activation, which is consistent with the strike-slip fault dislocation
353 source solution obtained by Okada (1992). However, the Okada model closed form solution is limited to elastic rock
354 material and a straight fault geometry. In our approach, dynamic and inhomogeneous variations of stress pattern
355 along a segmented strike-slip fault with off-fault damage is quantified. As a result of the relative plate slip motion,
356 the $\Delta\theta$ observed in the compression quadrants, dilatation quadrants, and at the tips of this strike-slip fault show
357 different temporal variation and reach a different asymptotic value. The fault releases energy that can temporally
358 generate a compressive stress field within the compression quadrants and form a local field stress through the
359 resultant stress with the tectonic stress field. However, a tensional stress field is generated within the dilatation
360 quadrants and form another different local stress field. Compared with previous studies, we used an innovative
361 segmented fault approach for a straight and curved fault geometry using smooth joints. This allows to account for
362 off-fault damage which is frequently observed along natural faults, e.g. in terms of exponential decrease of
363 microcrack damage with distance from fault core (Vermilye and Scholz, 1998; 1999). The maximum magnitudes of
364 the $\Delta\theta$ values drop with distance from the fault. It is important to note that the temporal variations of S_H associated
365 with earthquakes observed by the FGBS in the YSH borehole are compatible with the numerical modelling results
366 measured in the dilatation quadrants.

367 Hardebeck and Hauksson (2001) pointed out that the 1992 Joshua Tree and Landers earthquakes induced
368 substantial rotations of S_H along the SAF. Different temporal variation patterns are observed in the different regions,
369 i.e., increasing for the Emerson and Homestead Valley and decreasing for the Johnson Valley to a relatively stable
370 value (Hardebeck and Hauksson 2001). The increase in the azimuth of S_H in the Emerson region is consistent with
371 our modelling results within the dilatation quadrants. However, we may not exactly differentiate the temporal
372 evolution of the S_H orientation in the compression and the dilatation region associated with the SAF from this case
373 since the bins used for focal mechanism inversion straddle the fault trace irrespective of the quadrants generated
374 along the strike-slip fault (Hardebeck and Okada 2018). The $\Delta\theta$ values observed in dilatation quadrants drops at
375 first, then increases sharply and eventually reaches a stable value, which indicates that the azimuth of the S_H will
376 have a counterclockwise rotation which will later reverse itself. This is in agreement with the stress variation pattern
377 observed in the central zone of the Eastern California Shear Zone (ECSZ) (Hauksson 1994).

378 Yin and Rogers (1995) obtained a general rotation angle ($\Delta\alpha$) solution for strike-slip faulting. For positive $\Delta\alpha$,
379 the maximum stress axis rotates toward the normal to the fault, while for negative $\Delta\alpha$, the axis rotates away from
380 the normal to the fault. Based on the magnitudes of 38, 54, and 64 MPa for the minimum, intermediate and
381 maximum principal stresses respectively applied in our model, the stress ratio (δ) is equivalent to ~ 0.62 . Since the
382 angle between the Ganzi-Yushu fault and the far-field S_H axis is approximately 42° , the average stress drop ratio is
383 approximately 0.95 and 0.90 for linear faults and curved faults, respectively. This implies that the azimuth variation
384 of the S_H increases during the release of the strain energy. When applying this solution to our case, one limitation
385 should be noted: the areas close to and beyond the edge of the rupture area are not applicable (Yin and Rogers 1995).
386 However, we can obtain some understanding of the stress rotation with respect to the YSH borehole observation,
387 where the azimuth variation increases to a relatively stable value. It should be pointed out that Yin and Rogers'
388 solution cannot reflect the first drop pattern in the evolution of the stress azimuth variation in the modelling results
389 and in-situ observation data. It is more probable that the stress drop involving the Yushu earthquake reduced the
390 shear stress acting on the fault, causing stresses to rotate counter-clockwise (Bohnhoff et al. 2006). Additionally,

391 the stress rotations observed in the compression quadrants in our model drop dramatically to a relatively stable
 392 value, which are inconsistent with the rotation angle predicted by Yin and Rogers (1995). This discrepancy probably
 393 arises from the stress concentration gradually formed in the compression quadrants (Fig. 6).

394 One explanation for this discrepancy is given in the synoptic Fig. 11. During co-seismic slip, the fault releases
 395 energy that can temporally generate a compressive stress field (grey shaded area) within the compression quadrants
 396 and form a local field stress, S_H (post-Eq) through the resultant stress with the tectonic stress field, S_H (pre-Eq).
 397 Thus, the resultant stress orientation shows a counterclockwise rotation angle ($\Delta\theta$) away from the far-field tectonic
 398 stress, S_H (pre-Eq). However, a tensional stress field (orange shaded area) is generated within the dilatation
 399 quadrants and form a local stress field, S_H (post-Eq), indicating a clockwise rotation angle away from the S_H
 400 orientation prior to the earthquake occurrence (pre-Eq). It should be noted that there is an initial drop of $\Delta\theta$ within
 401 the dilatation quadrants. This can be explained with the local stress barriers or blocks formed ahead of the dilatation
 402 stress quadrants resulting from the compressive stress (red dotted arrows), but these will gradually will be tapered
 403 as fault slip motion continues.



404
 405 **Fig. 11** Synoptic picture of the assumed stress reorientation relative to the slip motion of the left-lateral strike-slip fault. Black
 406 solid arrows indicate the orientation of the maximum horizontal principal stress within compression quadrants after earthquake.
 407 Orange solid arrows show the orientation of the maximum horizontal principal stress within dilatation quadrants after
 408 earthquake.

410 The spatial distribution of maximum $\Delta\theta$ value substantially differs along the profile perpendicular to the fault,

411 i.e., the maximum $\Delta\theta$ drops with the distance from the fault. The discrepancy in the stress rotations between near-
412 and far-field agrees with the in-situ stress measurements along the SAF, where the orientation of the S_H measured
413 in the far-field is NNE. However, the azimuth of the S_H measured in the near field approximately rotates to EW
414 north of the fault and NW south of the fault (Sbar et al. 1979), perpendicular to the strike of the SAF in its immediate
415 vicinity (Fuchs and Muller 2001; Zoback et al. 1987). Stress reorientation patterns near the ground surface can be
416 precisely and continuously recorded using FGBS within YSH borehole arising from relative plate motion with
417 respect to the Ganzi-Yushu fault. The co-seismic stress reorientation data observed only from one borehole with
418 respect to the Ganzi-Yushu fault are a weak boundary condition. We suggest that more FGBS be used to observe the
419 reorientation of S_H near the crustal surface with high resolution within the compression and dilatation quadrants
420 along the strike-slip faults. Also, one can think about measuring strain and stress in deep boreholes close to the fault
421 if any boreholes become available in the future. Co-seismic slip distribution shows more drastic change when the
422 fault is curved (curved fault) and off-fault damage is simulated (elasto-plastic rock mass). Natural faults are never
423 continuous, but rather show complex structures along its trace, such as pull-apart regions, rotated blocks, isolated
424 lenses, etc. as shown in literature by Choi et al. (2012). Representing such structural complexity of natural faults by
425 smooth joint contact model in a bonded particle assembly is a first order approach to complex fault zone architecture.
426 Also, Aochi and Madariaga (2003) demonstrated that slip profile of the Izmit Turkey earthquake in 1999 was better
427 modelled and match with better with observations, when the fault is represented as curved and segmented,
428 compared to linear and continuous. In this 2D modelling, we assumed that the stress changes near the Ganzi-Yushu
429 fault is mainly associated with Yushu main earthquake (EQ2). The existing additional faults may have moved by the
430 Yushu earthquake and may have influenced the stress reorientation at YSH borehole. However, as seen in the
431 earthquake hypocenter map, those fault traces beside the Ganzi-Yushu fault do not host any of the earthquake $M > 3$
432 hypocenters. Therefore, we limit our modelling to only the trace of Ganzi-Yushu fault representing major seismo-
433 tectonic energy release in the study area. Simulating multiple fault traces and investigating the effect of the
434 additional faults on the co-seismic stress distribution and stress orientation at YSH borehole are suggested for future

435 study. In addition, this 2D model for co-seismic slip provides a first-order estimate of the impacts on the local stress
436 field of such strike-slip motion, assuming a full fault trace rupture. An earthquake fault seldom ruptures in its entire
437 plane. Partial and segmented ruptures will be taken into account in future modelling. Accordingly, the modelling of
438 stress orientation associated with the YSH borehole is a qualitative analysis rather than a quantitative estimation.
439 The present study suggests that a PFC 3D model taking into account the detailed complex geological conditions and
440 the multistage rupture process related to the Ganzi-Yushu fault is needed. We do not consider the effect of fluids.
441 The presence of fluid in the rock mass and in the fault could have different effects on the overall behavior of stress
442 reorientation around and near to a rupturing fault. If the fault is fluid filled, the fault slips earlier and slowly during
443 the tectonic loading compared to the fluid-free fault situation. In addition, the fluid-filled fault dilation results in
444 normal stress increase. Normal stress increase would compact the pore volume, and due to fluid incompressibility
445 and trapped pore fluid, the rock mass can become over-pressurized. Over-pressurized, trapped fluid in a fault can
446 result in (a) fault tip propagation, (b) local stress concentration and (c) in stress reorientation around the fault
447 (before the dynamic rupture) due to stress shadowing effect (Yoon et al. 2015a). If the fault is partially fluid-filled
448 or filled heterogeneously with fluid, the effect of fluid presence would be more complex.

449

450 **7 Conclusion**

451 The $\Delta\theta$ values observed with the FGBS system in the YSH borehole near the Ganzi-Yushu fault first decreased
452 and then increased substantially to an asymptotic value in response to the Yushu earthquakes. In order to interpret
453 this stress reorientation phenomenon and provide insights into the spatiotemporal reorientation pattern of S_H
454 regarding the strike-slip fault during earthquake occurrence, we present a discrete element modelling using PFC2D
455 and set up four scenarios of fault dynamic rupture (LE, LEP, CE and CEP). The modelling of $\Delta\theta$ variation patterns
456 during the activation of the smooth joints for each scenario agrees with in-situ observations in the YSH borehole
457 during earthquake occurrence, which indicates that the stress rotation contributed to the Yushu earthquake. The
458 modelling reveals that dilatation and compression quadrants are formed around a strike-slipping fault, resulting in

459 different spatiotemporal changes of the $\Delta\theta$ value. The $\Delta\theta$ value in the compression quadrants drops substantially by
460 co-seismic slip then finally approaches an asymptotic value. In the dilatation quadrants, $\Delta\theta$ value drops by co-
461 seismic slip, then increases sharply and finally reaches a stable value. During co-seismic slip, the fault releases
462 energy that can temporally generate a compressive stress field within the compression quadrants and form a local
463 field stress through the resultant stress with the tectonic stress field. However, a tensional stress field is generated
464 within the dilatation quadrants and form a local stress field indicating a clockwise rotation angle away from the S_H
465 orientation prior to the earthquake occurrence. In addition, the $\Delta\theta$ value decreases with increasing distance from
466 the location of rupture source. The structural complexity and off-fault damage by co-seismic fault slip have a
467 significant impact on the stress field alteration near the rupturing source. In order to understand the stress
468 reorientation in more detail within the quadrants, we suggest that higher resolution FGBS data should be used in
469 combination with deformation measurement methods (e.g., InSAR measurements), which can help to understand
470 the stress reorientations before, during and after occurrence of large earthquakes.

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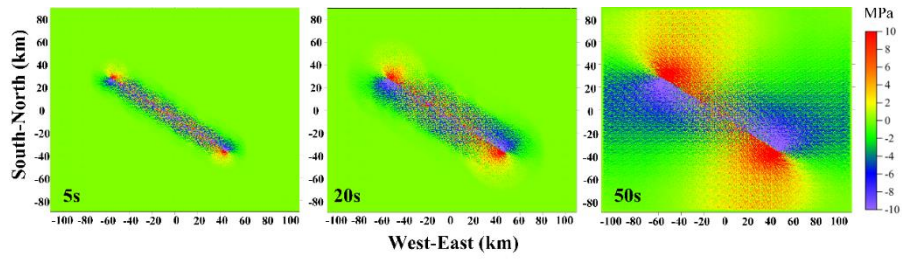


Fig. S1 Spatiotemporal evolution of compression (red) and dilatation (blue) stress quadrants for the LE scenario.

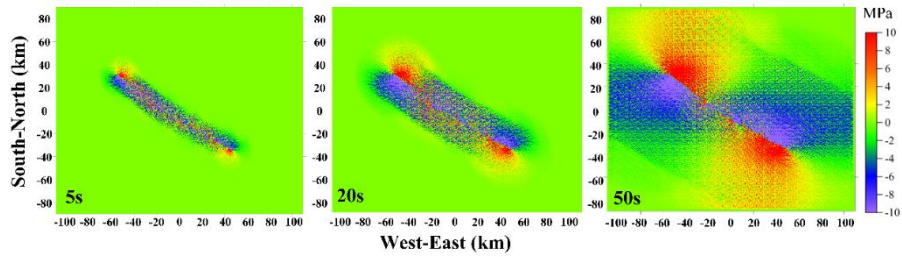


Fig. S2 Spatiotemporal evolution of compression (red) and dilatation (blue) stress quadrants for the CE scenario.

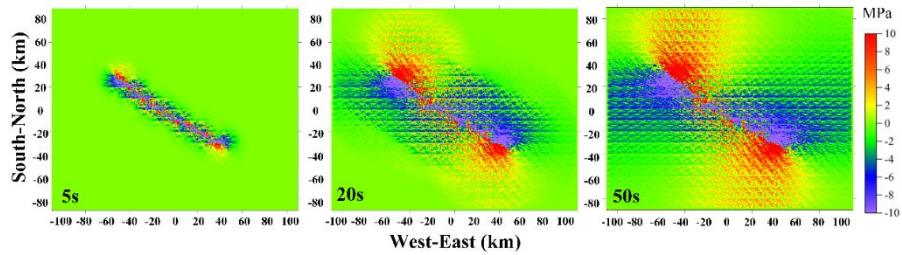


Fig. S3 Spatiotemporal evolution of compression (red) and dilatation (blue) stress quadrants for the CEP scenario.