

DESMEX WWU MÜNSTER
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 BGR Bundesanstalt für Geowissenschaften und Rohstoffe
 supracon

Multivariate processing of AFMAG data

Application to the Gobabis demonstration survey (Namibia)

Anneke Thiede, Markus Schiffler, Michael Becken, Michael Schneider,
 Stefan Bräuer, Ronny Stolz, Annika Steuer, Carsten Plath

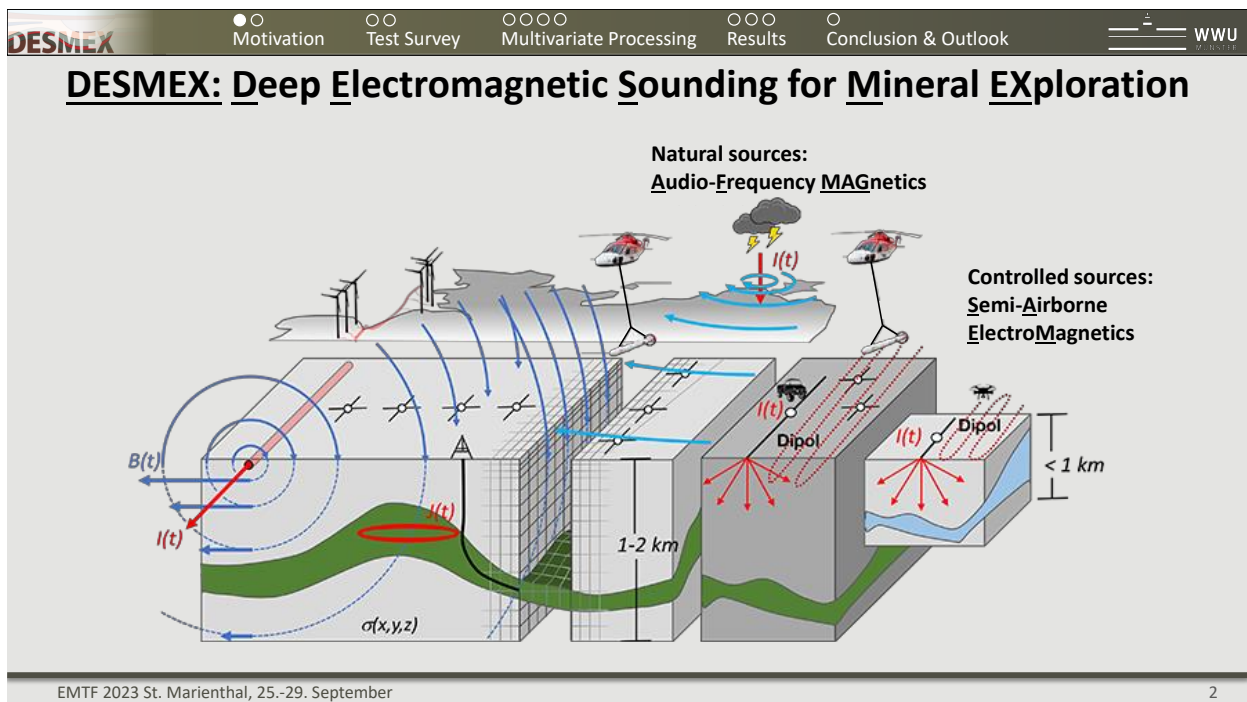
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DESMEX: Deep Electromagnetic Sounding for Mineral Exploration

Natural sources: Audio-Frequency MAGnetics


Controlled sources: Semi-Airborne ElectroMagnetics



$B(t)$, $I(t)$, $\sigma(x,y,z)$, 1-2 km, Dipol, $I(t)$, Dipol, $I(t)$, $< 1 \text{ km}$

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What do we need?

- 1) Sensor platform (previous talk by Schiffler et al.)
- 2) Demonstration survey in a suitable test area
- 3) Software:
 - Processing (WWU, IPHT)
 - Inversion (3D: custEM @LIAG, IPHT)

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Requirements:

- 1) No cultural noise
- 2) Large-scale and strong lateral conductivity contrasts
- 3) Potential of mineralization

Kalahari Copper Belt

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Tectonics

- KCB:
 - Cu, Ag, Pb, Zn, Fe sulphides
- Covered by Kalahari sands in NE part
- Mining activities at Klein Aub, Witvlei and Ghanzi Ridge

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Survey

- Area: 30 x 36 km²
- Set up:
 - Flight lines: 31/37 (1 km spacing, 890.6 km)
 - Tie lines: 5/6 (5 km spacing, 176.8 km)
 - line spacing: 1km / 5km
- Ground stations (\vec{E} and \vec{B} -field):
 - 1 SQUID base station
 - 3 induction coil stations

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Bivariate Approach

- ✓ overall good results if signal/noise ration high enough
- fails on sites affected by coherent noise

Multivariate Approach

- computation more sophisticated
- ✓ better results for (coherent) noise-affected sites

airborne data strongly affected by coherent (motional) noise!

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N Fourier coefficients of frequency band belonging to target frequency f at i th time window:

$k = 1 \dots k$ total number of channels including all sites

N Number of Fourier coefficients in frequency band

$j = 1 \dots J$ Number of sites

$N \times K$ matrix; each column representing a channel with N Fourier coefficients

Complex-valued matrix representing E- and H-field observed at different sites j

$$\mathbf{X}_i = \begin{pmatrix} \mathbf{b}_{1i} \\ \mathbf{e}_{1i} \\ \vdots \\ \mathbf{b}_{ji} \\ \mathbf{e}_{ji} \end{pmatrix}^T = \mathbf{U}_i \mathbf{s}_i \mathbf{V}_i^* + \boldsymbol{\varepsilon}_i$$

SVD with ideally 2 dominant singular values representing natural signal

Incoherent noise

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Multivariate MT Processing Codes:

Egbert (1997)

- iteration over time windows to improve estimates

Smirnov & Egbert (2012)

- based on Egbert (1997), allows for incomplete data sets

Hering (2019)

- treats each time window separately and then searches for best estimate

➔

AFMAG Requirements:

- Flexible Channel Management
- Read INS Data
- Optimized Sequential Processing

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Timeseries

Pre-Processing

- resampling
- synchronizing

Processing

for f = target frequencies

- Decimation
- Windowing
- FFT and Filtering
- Calibration, Remove noisy frequencies
- Eigenvalue decomposition
- TF estimation
- end

Post-Processing

- Outlier detection (Mahalanobis distance)
- Spatial averaging

Transfer Functions

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for $f =$ target frequencies
 Decimation
 Windowing
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 end

→ Multiples of $\frac{1}{f_{target}}$ [s]

L Windows over induction volume

Skin depth dependent

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for $f =$ target frequencies
 Decimation
 Windowing
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 TF estimation
 end

Spectral density matrix \mathbf{S}

Noise covariance matrix $\mathbf{\Sigma}$

$\tilde{\mathbf{S}} = \mathbf{\Sigma}^{-\frac{1}{2}} \mathbf{S} \mathbf{\Sigma}^{-\frac{1}{2}}$ Scaling by noise covariance matrix $\mathbf{\Sigma}$

$\tilde{\mathbf{S}} \tilde{\mathbf{U}} = \lambda \tilde{\mathbf{U}}$ Calculate eigenvalues λ and -vectors $\tilde{\mathbf{U}}$

$\mathbf{U}_{est} = \mathbf{\Sigma}^{-\frac{1}{2}} \tilde{\mathbf{U}}_{12} (\tilde{\mathbf{U}}_{12}^* \mathbf{\Sigma}^{-1} \tilde{\mathbf{U}}_{12})^{-1}$ Rescaling

$\tilde{\mathbf{U}}_{12}$: $K \times 2$ vector from $\tilde{\mathbf{U}}$, corresponding to first 2 eigenvalues

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for f = target frequencies

- Decimation
- Windowing
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- Eigenvalue decomposition
- TF estimation

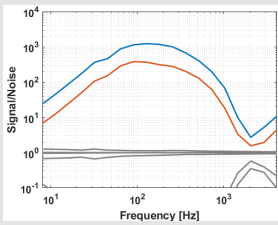
end

$$\tilde{S} = \Sigma^{-\frac{1}{2}} S \Sigma^{-\frac{1}{2}}$$

Scaling by noise covariance matrix Σ

$$\tilde{S}\tilde{U} = \lambda\tilde{U}$$

Calculate eigenvalues λ and -vectors \tilde{U}



Median eigenvalues of 1 flight

Bird with KRO-B03

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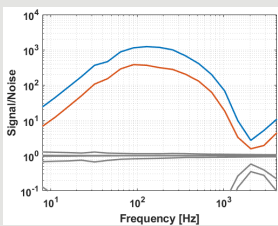
for f = target frequencies

- Decimation
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- Calibration, Remove noisy frequencies
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- TF estimation

end

$$\tilde{S}\tilde{U} = \lambda\tilde{U}$$

Calculate eigenvalues λ and -vectors \tilde{U}



Median eigenvalues of 1 flight

Bird with KRO-B03

$$U_{est} = \Sigma^{-\frac{1}{2}} \tilde{U}_{12} (\tilde{U}_{12}^* \Sigma^{-1} \tilde{U}_{12})^{-1}$$

Rescaling

U_{est} : Entries used for TF calculation

Induction Arrows

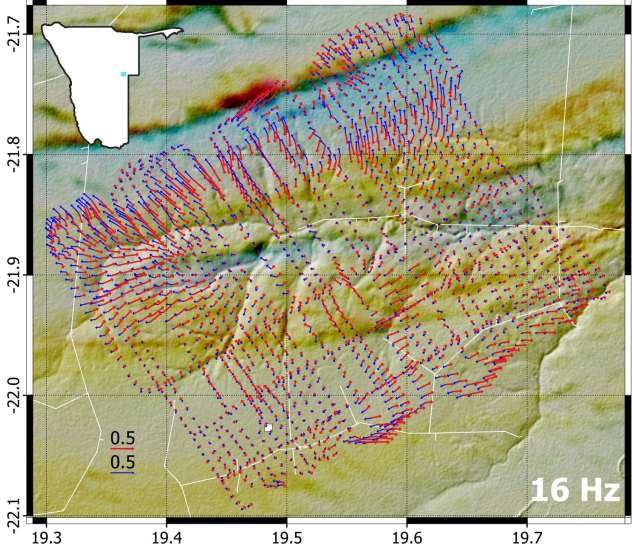
$$[T_{zx} \quad T_{zy}] = [\eta_{z,bird}^{\lambda_1} \quad \eta_{z,bird}^{\lambda_2}] \left(\begin{bmatrix} \eta_{x,grad}^{\lambda_1} & \eta_{x,grad}^{\lambda_2} \\ \eta_{y,grad}^{\lambda_1} & \eta_{y,grad}^{\lambda_2} \end{bmatrix} \right)^{-1}$$

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Processing settings

- $\rho_{bg} = 1000 \Omega m$ for windowing
- $L = 11$ windows
- Reference: KRO-B03
- Problems:
 - Time drift (bird): F1, F2
 - Thunder storm activity: F1

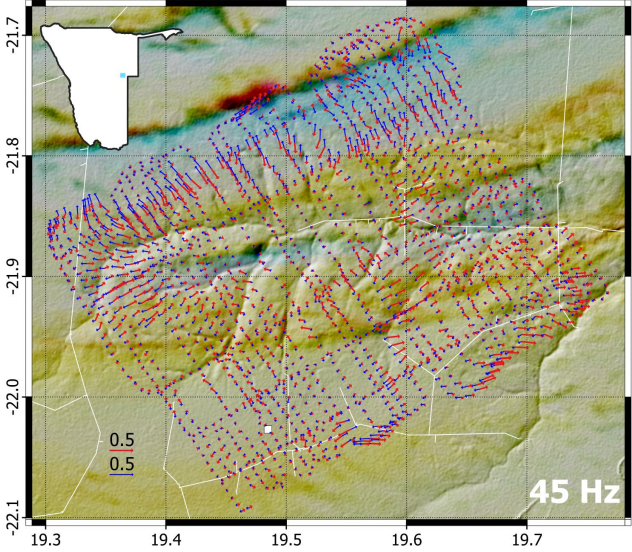


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Processing settings

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- Problems:
 - Time drift (bird): F1, F2
 - Thunder storm activity: F1

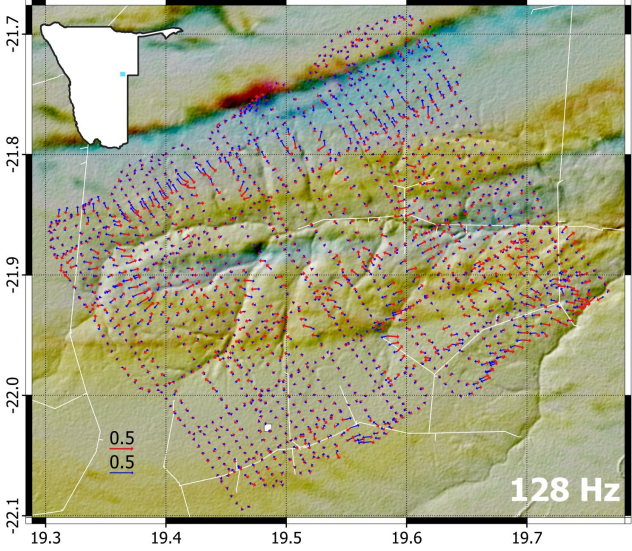


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Processing settings

- $\rho_{bg} = 1000 \Omega m$ for windowing
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- Reference: KRO-B03
- Problems:
 - Time drift (bird): F1, F2
 - Thunder storm activity: F1

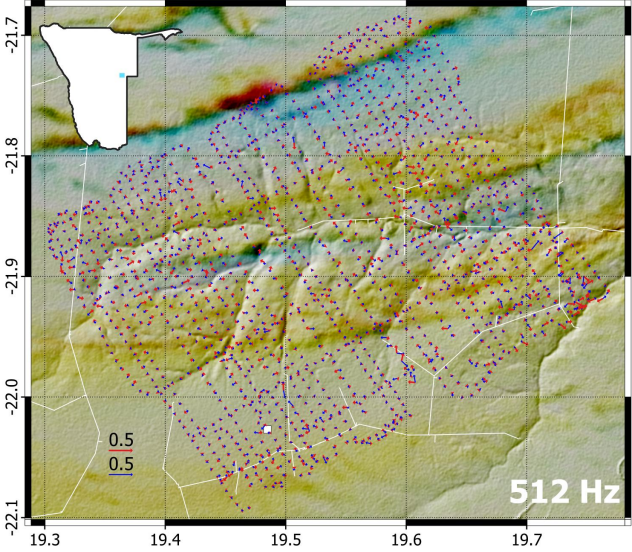


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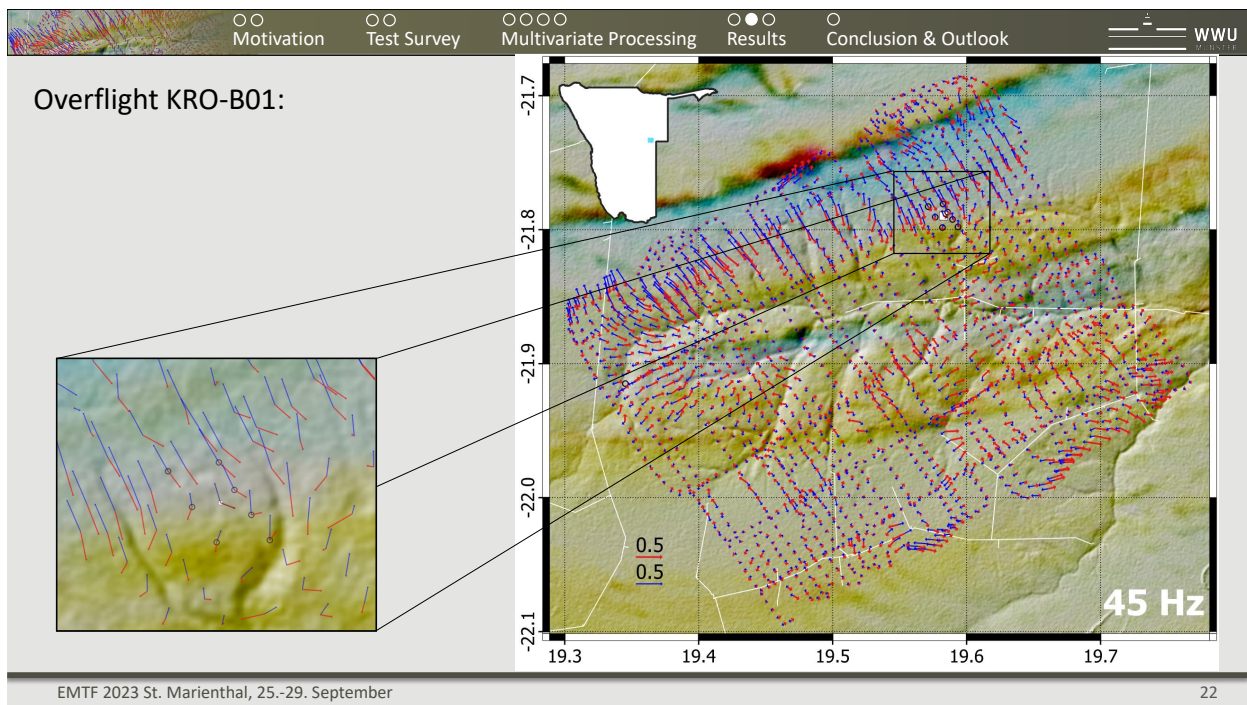
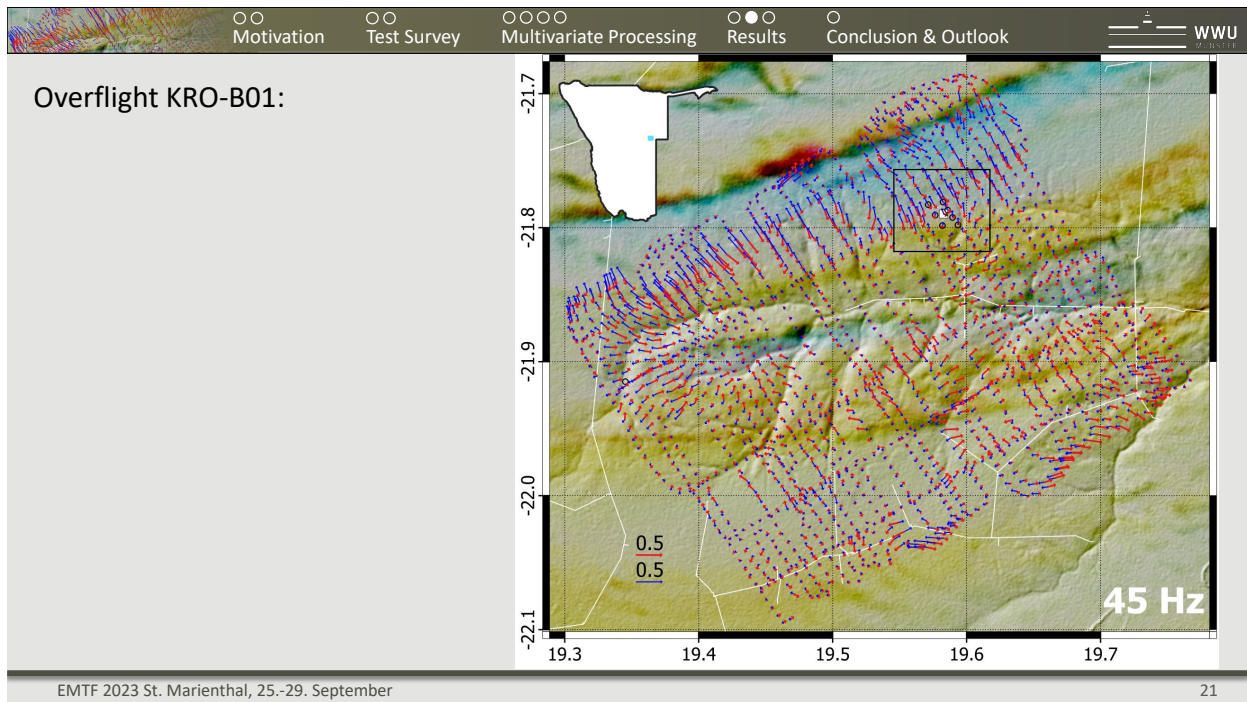
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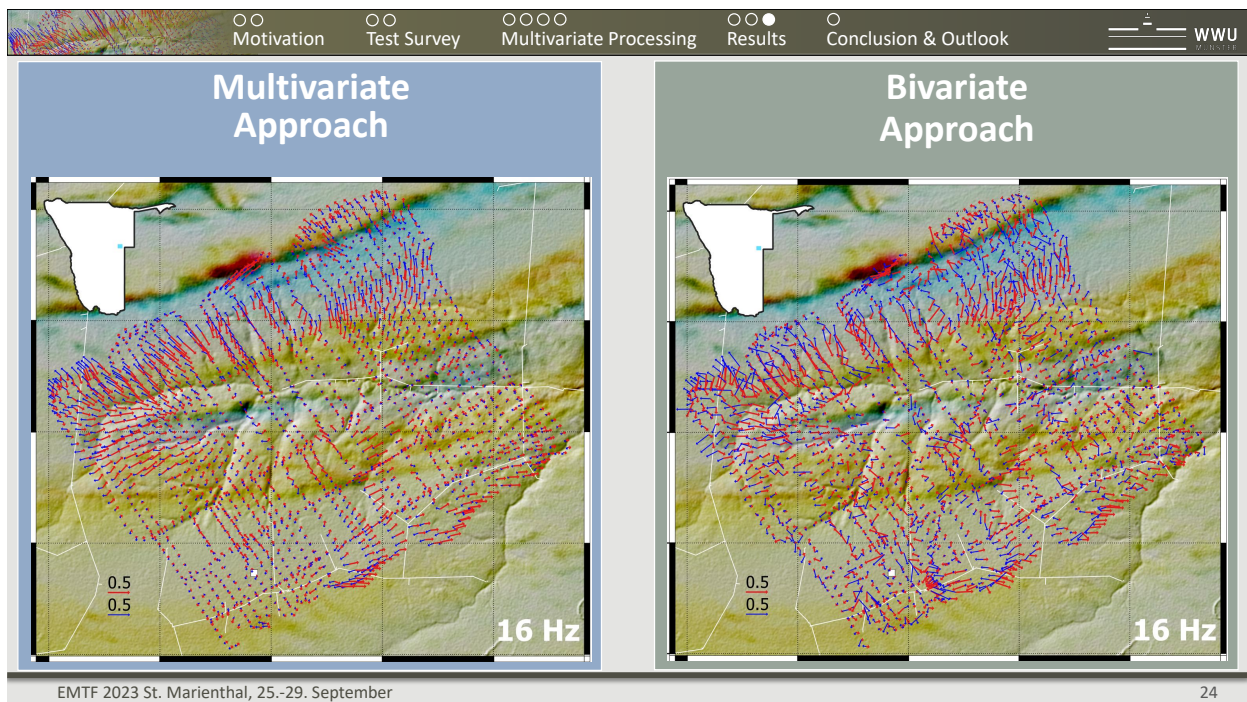
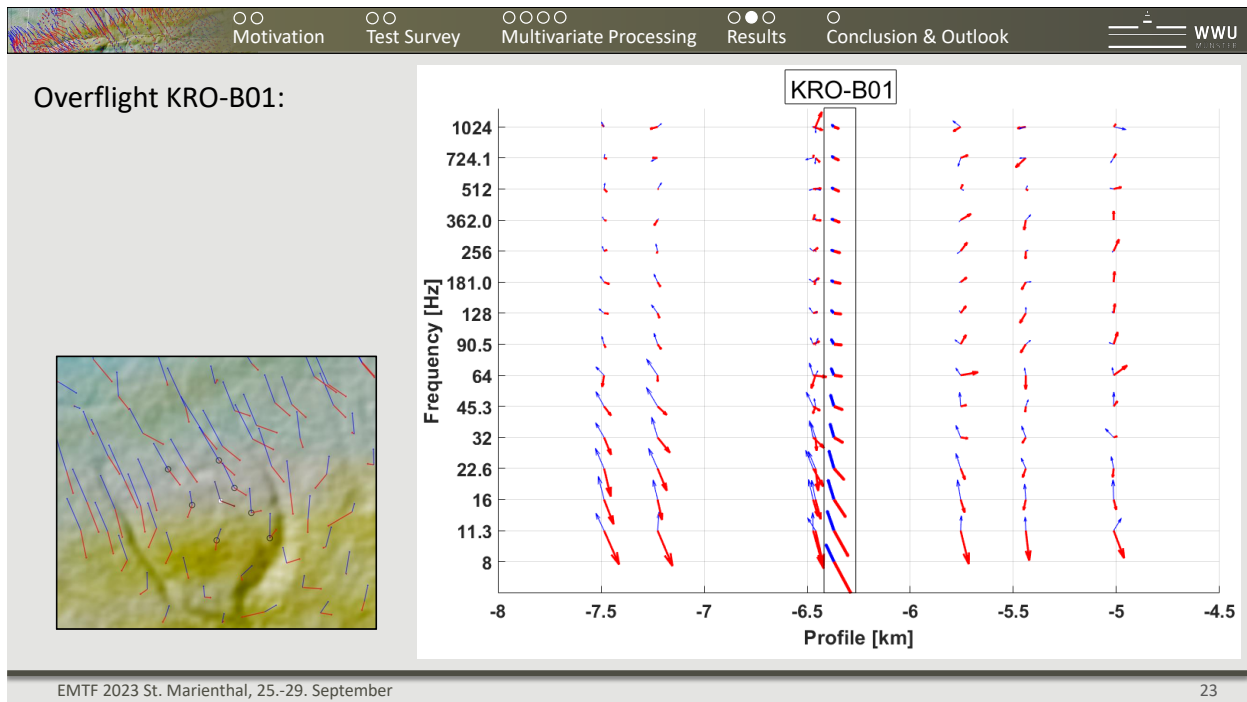
Processing settings


- $\rho_{bg} = 1000 \Omega m$ for windowing
- $L = 11$ windows
- Reference: KRO-B03
- Problems:
 - Time drift (bird): F1, F2
 - Thunder storm activity: F1



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Survey

- Successful 1st DESMEX AFMAG survey using SQUID bird

Data quality

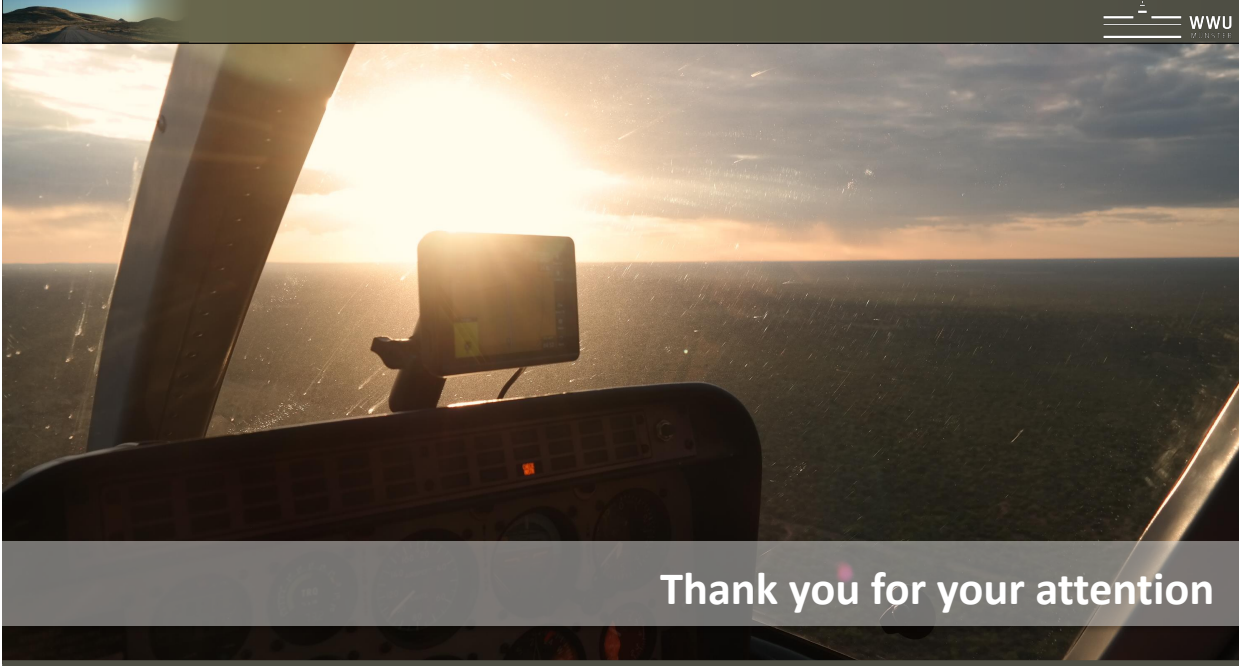
- Smooth transfer functions: 11 Hz to 1024 Hz
- Broader frequency range than commercial systems
- good data quality: 16 Hz to 724 Hz
- In agreement with geological strike direction

Next steps

- Improve averaging
- 3D inversion using custEM
- Optimization of induction coil bird (Poster)

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Thank you for your attention

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